



IDAJ公司

高精度高取样频率
被控发动机模型
GT-POWER xRT应用

IDAJ中国
GT小组

目录

1. GT-SUIET中发动机模型简介
2. GT-POWER xRT新功能
3. GT-SUITE中发动机在XIL中应用
4. 结论

■ GT-SUITE 基于物理模型

- N-S 方程求解
- 基于曲轴转角计算的喷射，燃烧，排放

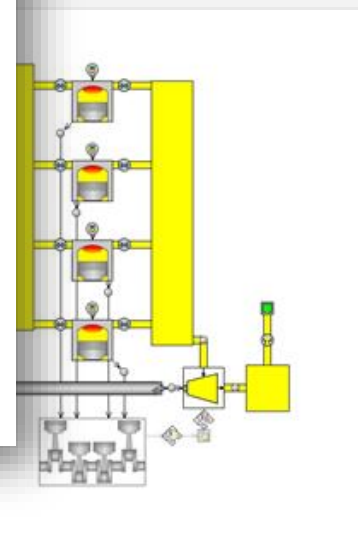
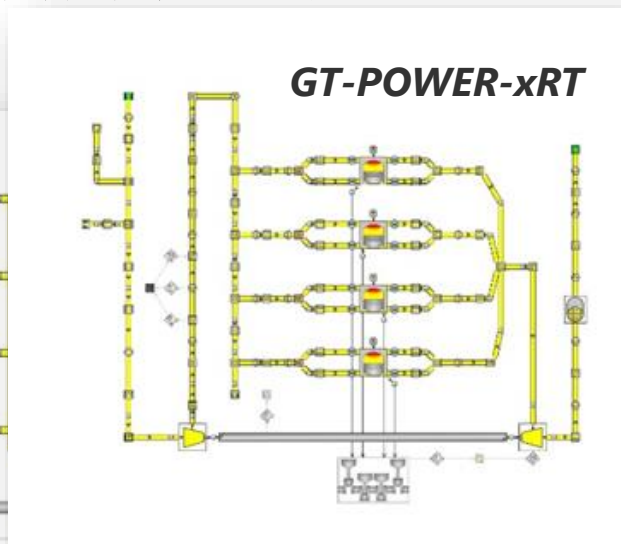
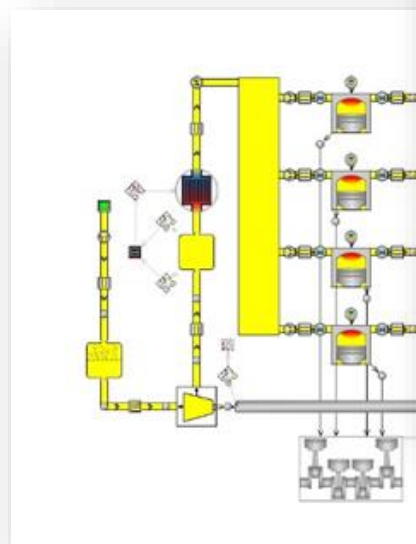
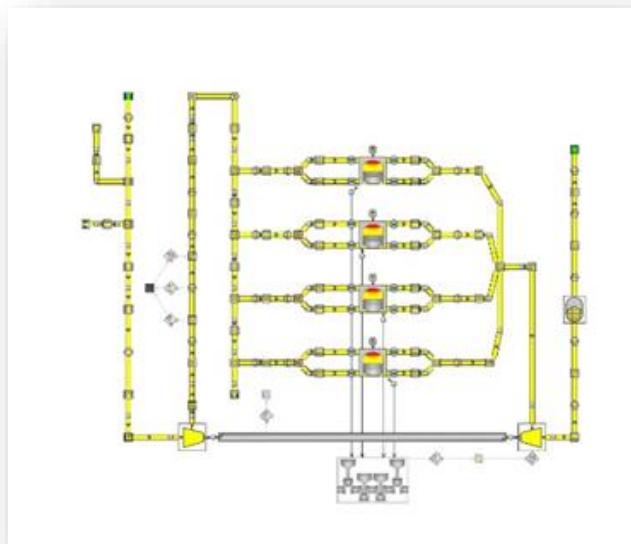
■ 瞬态动力学模型

■ 完全可调的 模型能够平衡：

- 计算精度和计算速度
- 预测性的和测量辅助的精度

■ 可调的Adjustable 模型保真度/速度

- (30 - 100 x RT): 详细的气体动力学, 适合发动机设计
- (1 - 3 x RT): 较粗糙的气体动力学计算, 适合 SiL
- (0.3 - 1 x RT): 速度调整. 适合 HiL
- (0.1 - 1 x RT): **GT-POWER-xRT** 采用详细的气体动力学. 适合 SiL & HiL

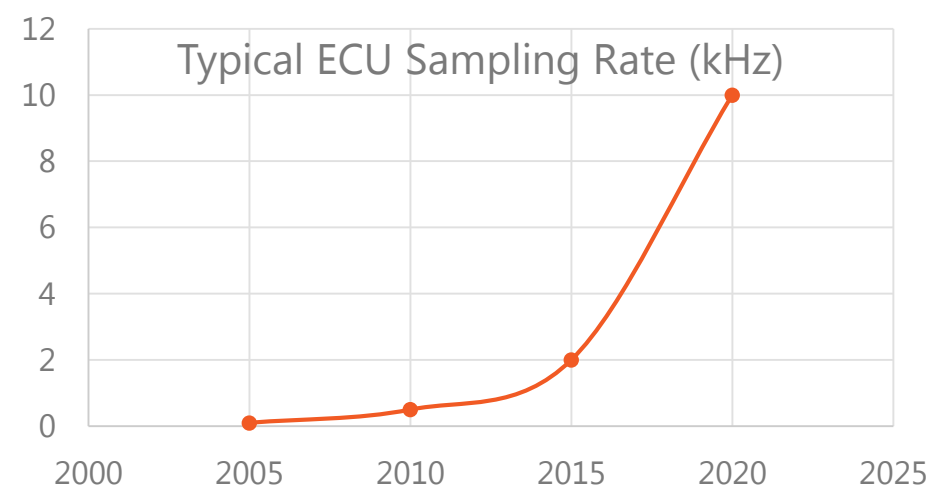


- GT-POWER-xRT是一个专门的发动机模型求解器：
 - 维护核心GT-POWER解决方案
 - 达到速度~10倍以上的 GT-POWER 求解器

- GT-POWER-xRT 从以下方面提高速度：
 - 允许性能优化的GT模板和选项的子集
 - “surgical” 求解过程的修改，对结果的影响很小

■ 为什么开发 xRT?

- 在HiL系统上以一个小的固定时间步长运行详细的引擎模型
- 运行引擎模型在高引擎转速(如15000rpm)和/或大缸数
- ECU 更高的取样频率
 - 喷射控制
 - 燃烧控制
 - 曲柄转角位置
- 避免把时间花在简化发动机模型几何形状上



- 例子: 3.4L Twin Turbo V6 GDI
- 122 个流体控制体
- 固定时间步长= 0.06ms $\rightarrow$ 2.2°CA @ 6000rpm
- 实时因子: 0.89
- 燃烧模型: SIWI

89s Clock time for
100s Simulation time

INFO Total Number of Parts = 341

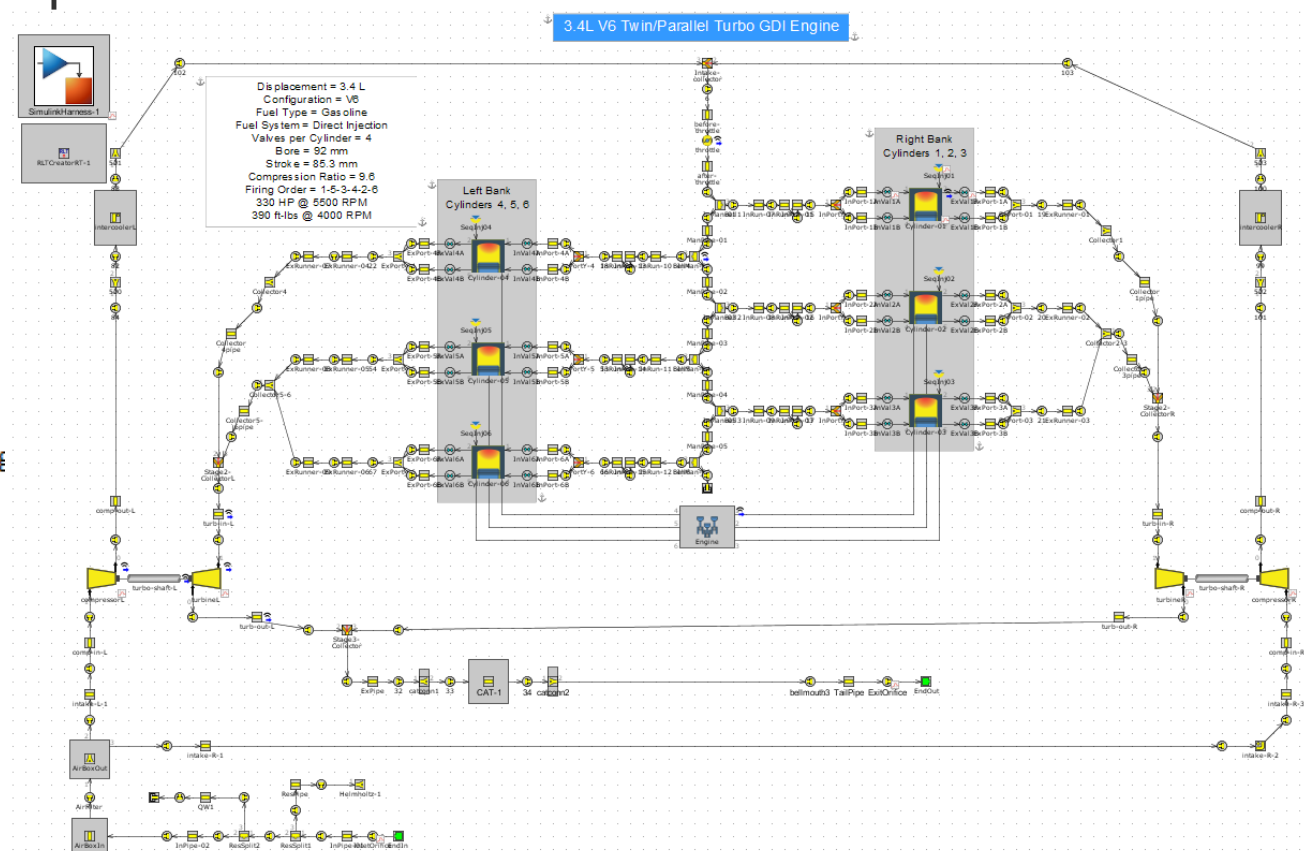
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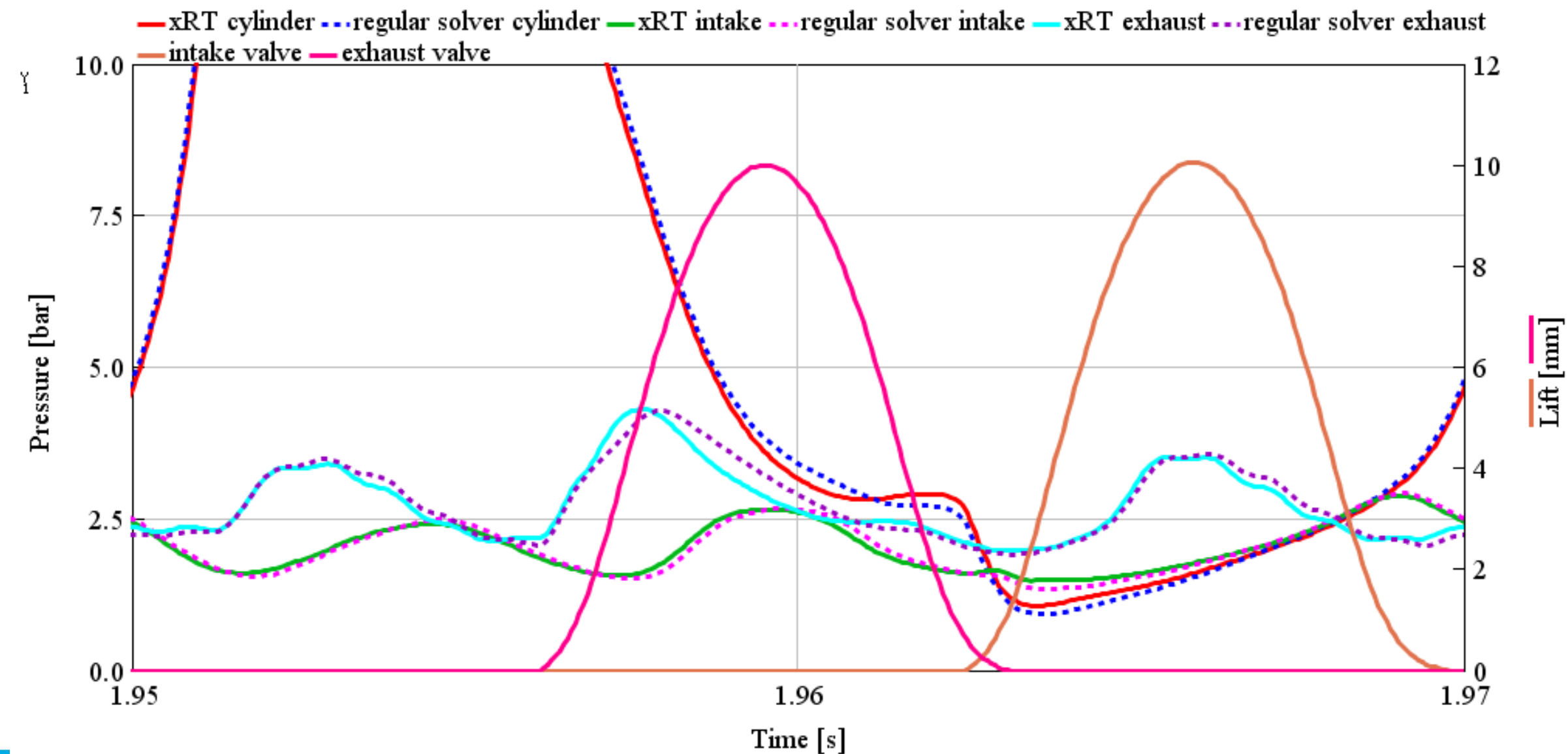
CASE COMPUTATIONS: Elapsed Time: 000:01:29.04

END OF RUN

Tue Nov 13 14:50:53 2018 Creating results (.gdx) file...

Tue Nov 13 14:50:53 2018 GDX file Step6.gdx generated successfully.





- V16 76.3l Twin Turbo Diesel
- 流体控制体总数：118
- 时间步长=0.12ms→1.4°CA@ 1900rpm
- 实时因子: 0.8
- 燃烧模型: DIPulse

80s Clock time for
100s Simulation time

INFO Total Number of Parts = 305

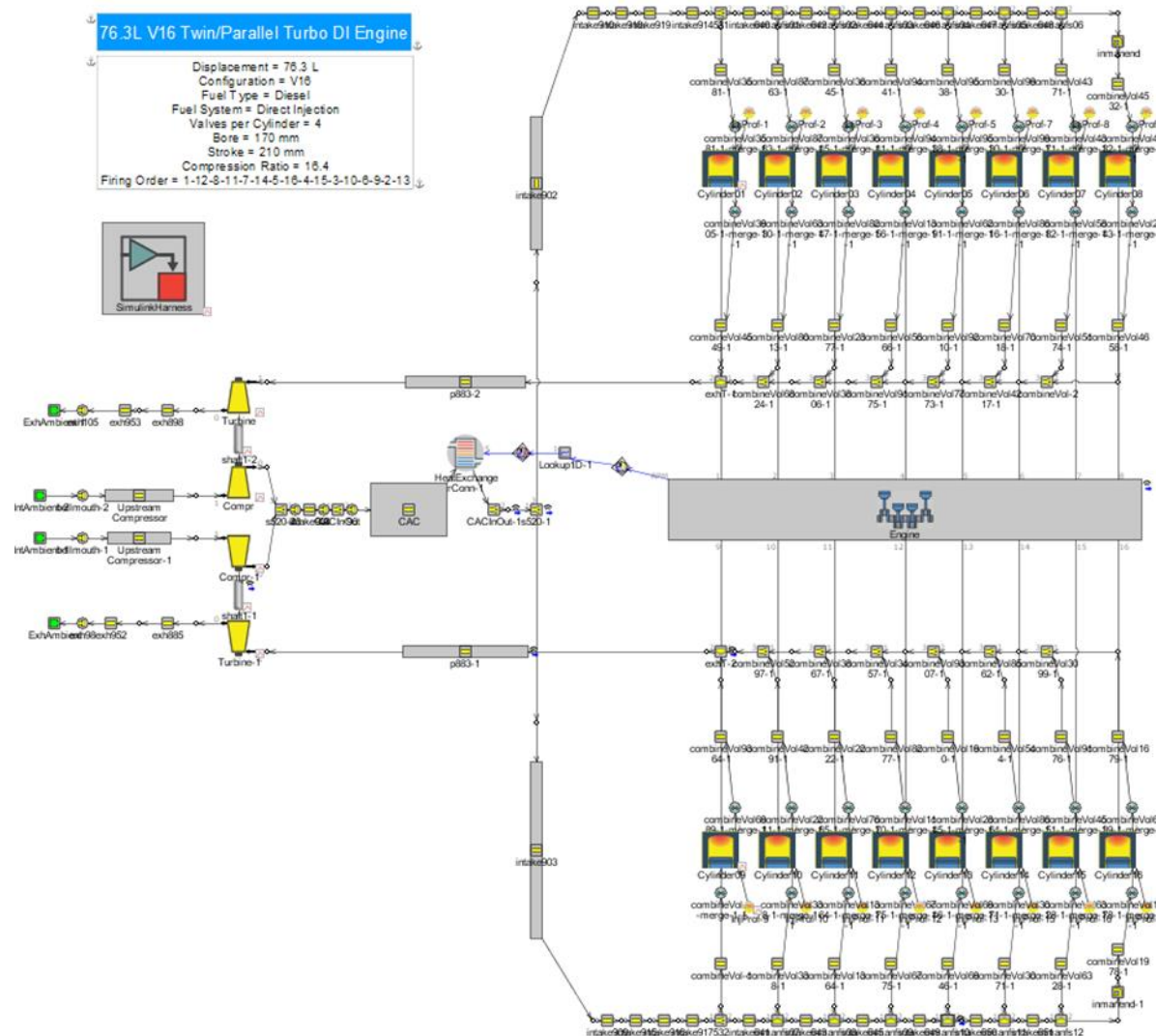
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CASE COMPUTATIONS: Elapsed Time: 000:01:19.82

END OF RUN

Wed Feb 6 07:18:55 2019 Creating results (.gdx) file...

Wed Feb 6 07:18:55 2019 GDX file Step7.gdx generated successfully.

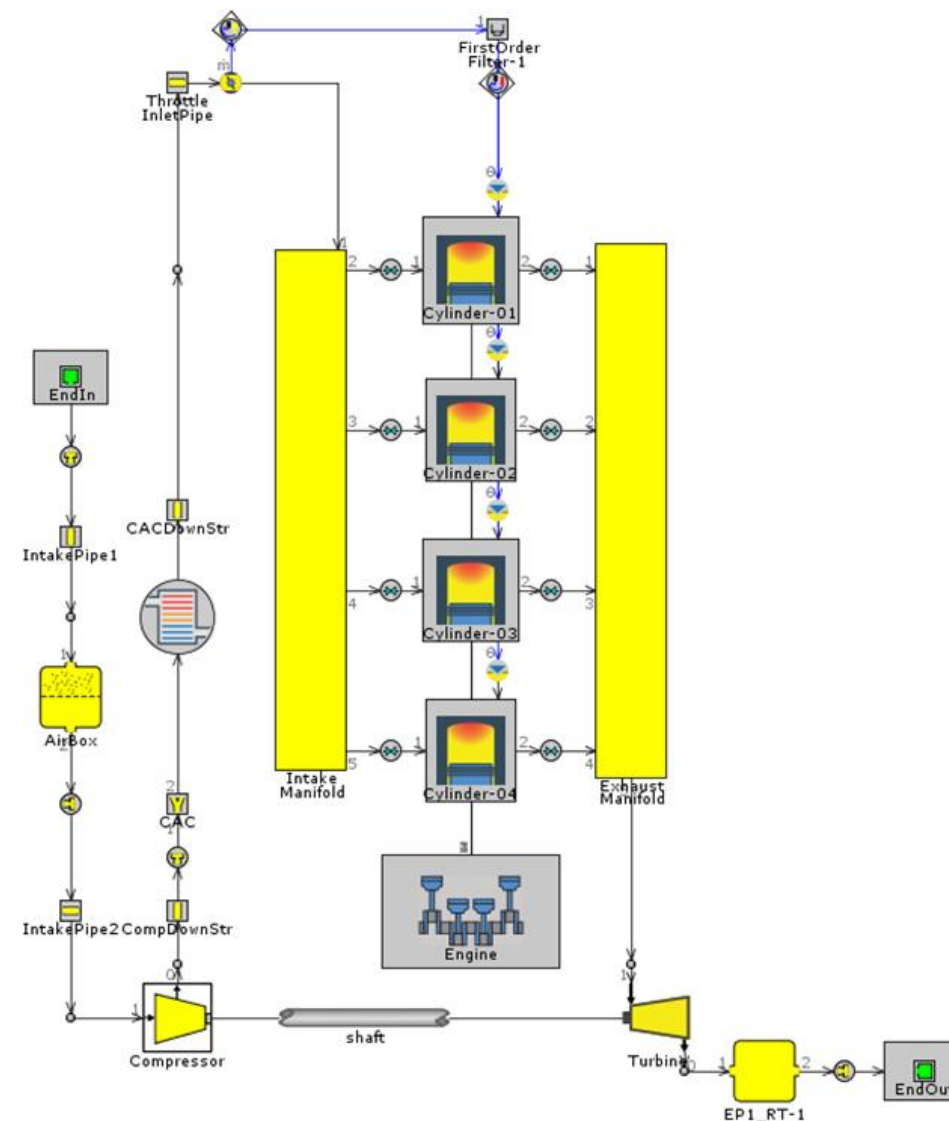


Model can be provided upon request.

- 例子: 4 Cylinder SI Turbo
- 10.37s 计算 100s的实例

```
10 3 5.E-19 1.138526E-02 -2.E-18
10 4 5.E-19 1.138526E-02 -2.E-18
10 5 5.E-19 1.138526E-02 -2.E-18
.
Total number of FSPLITS 5
Detailed fsplits:.....3
.
INFO Total Number of Parts = 73
.
INFO The Performance plot is turned on. Screen and .out file output along
.....with the stop simulation ability will be suppressed to improve the
.....performance measurement. This plot can be turned on or off from
.....Output Setup -> General.
.
CASE COMPUTATIONS: Elapsed Time: 000:00:10.37
FINAL COMPUTATIONS: Elapsed Time: 000:00:10.39
.
END OF RUN
Fri Aug 17 07:47:57 2018 Creating results (.gdx) file...
Fri Aug 17 07:47:57 2018 GDX file 4cyl_RunTimeTest-V2019.gdx generated successfull
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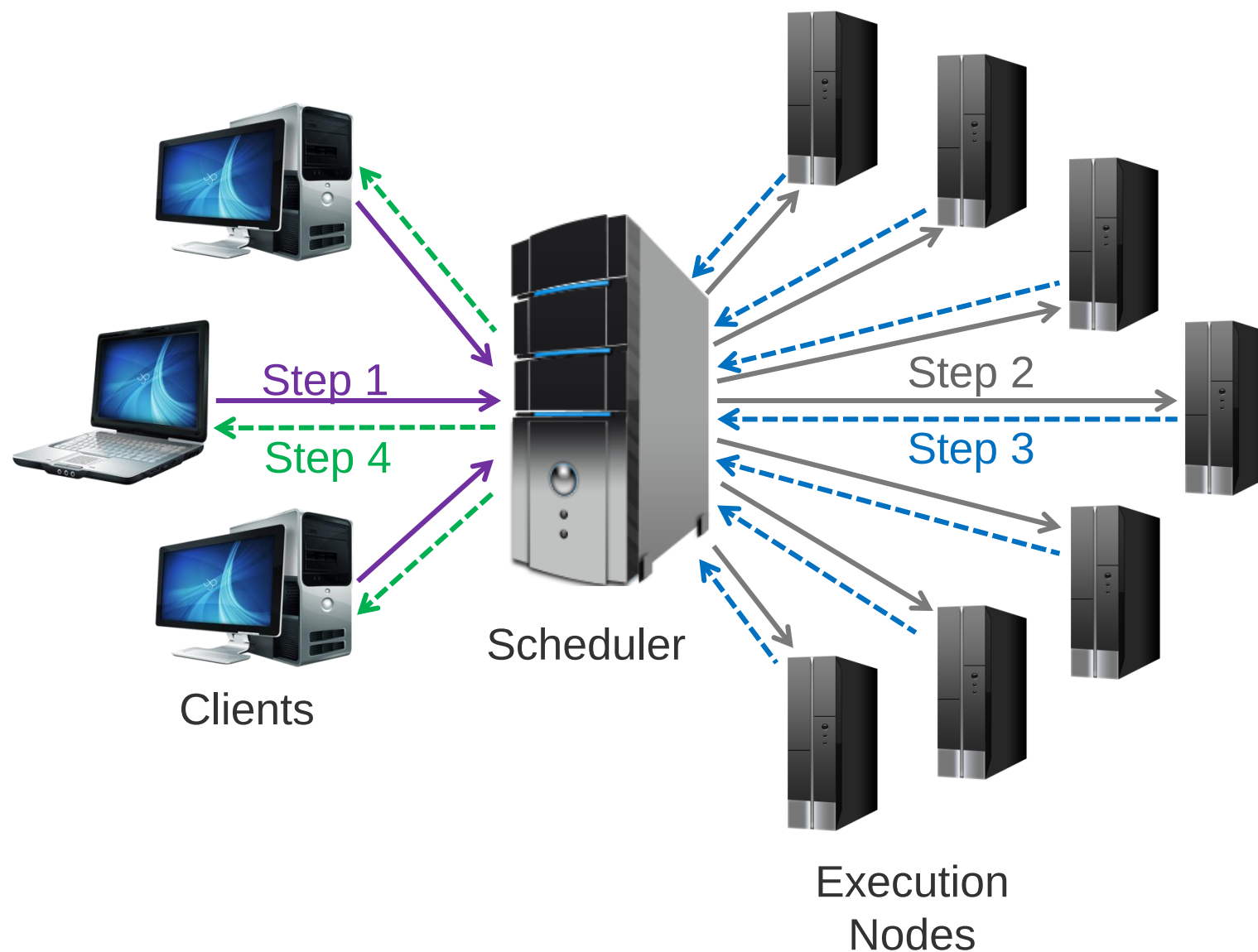
- 实时因子: 0.1037
 - 有4个气缸和气路模型



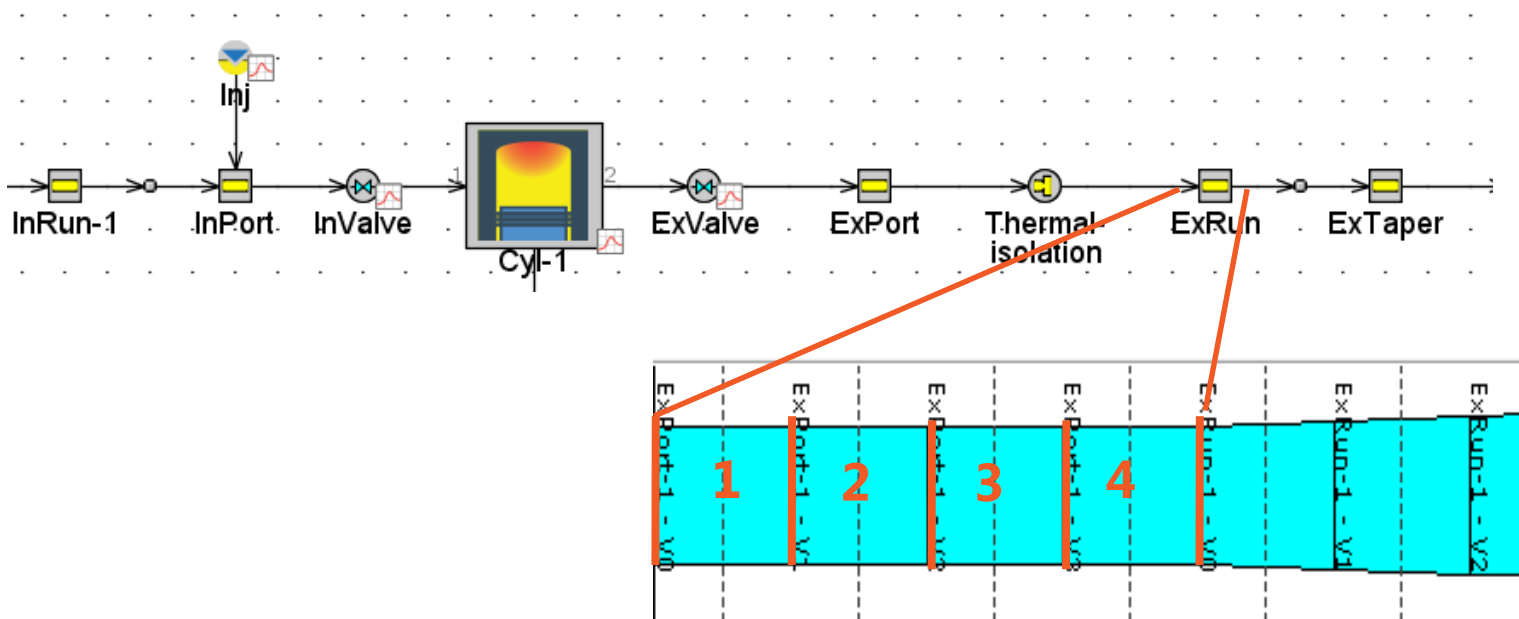
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- 提高了生产率
- 并行运行多个案例
- 优化



- 将一个 pipe part 分成多个控制体
- 可以研究多控制体和单个控制体的差别
- 主要适用于 SI 发动机的 intake/exhaust runners/ports



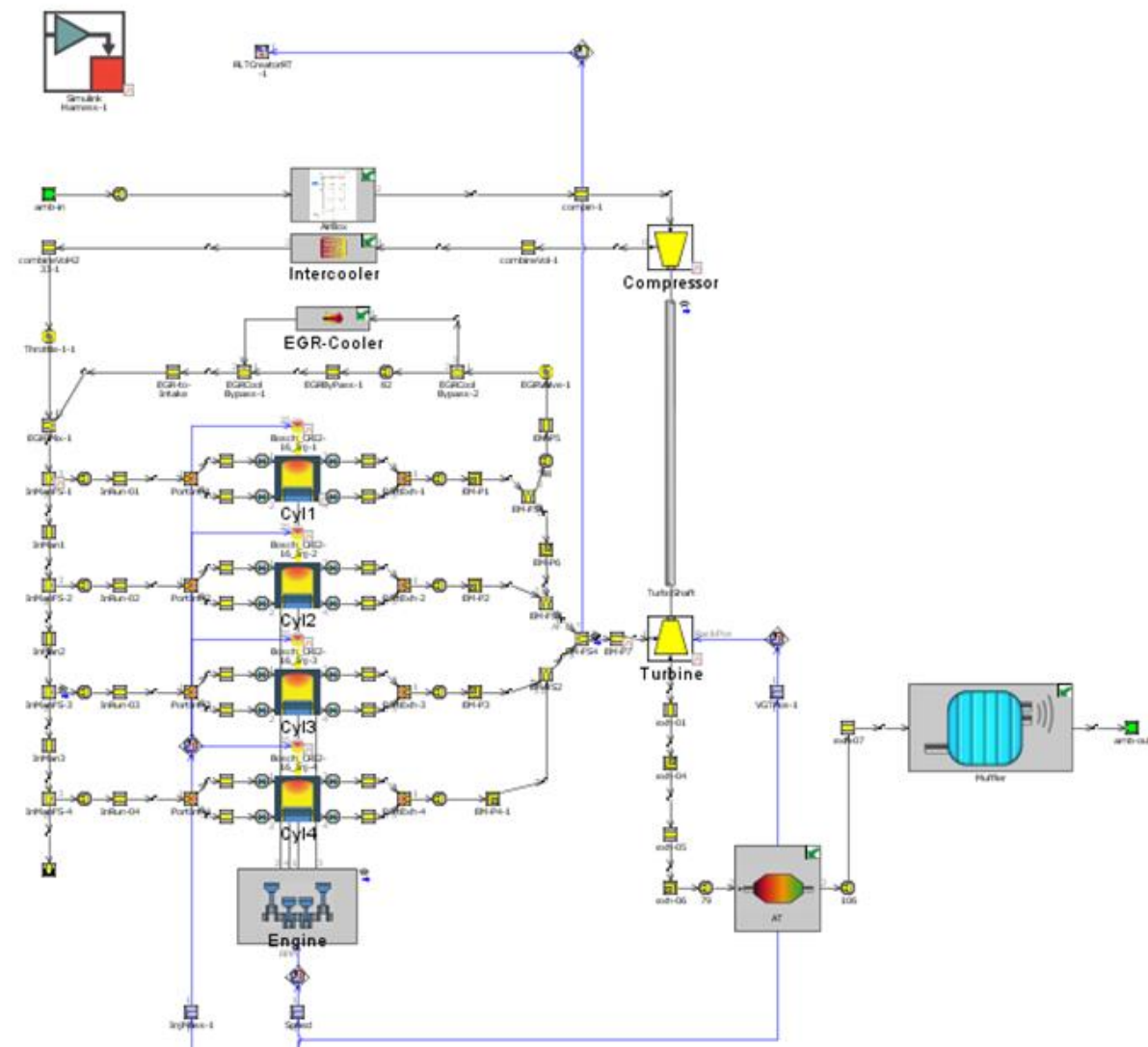
- 简化 EngCylTWallSoln 的输入变量
 - Head
 - Piston
 - Cylinder liner
 - Each valve
- 发动机散热的热质量温度
- Cylinder, pipe* 和 flowsplit 的传热传感器
- v2019 b2 可用

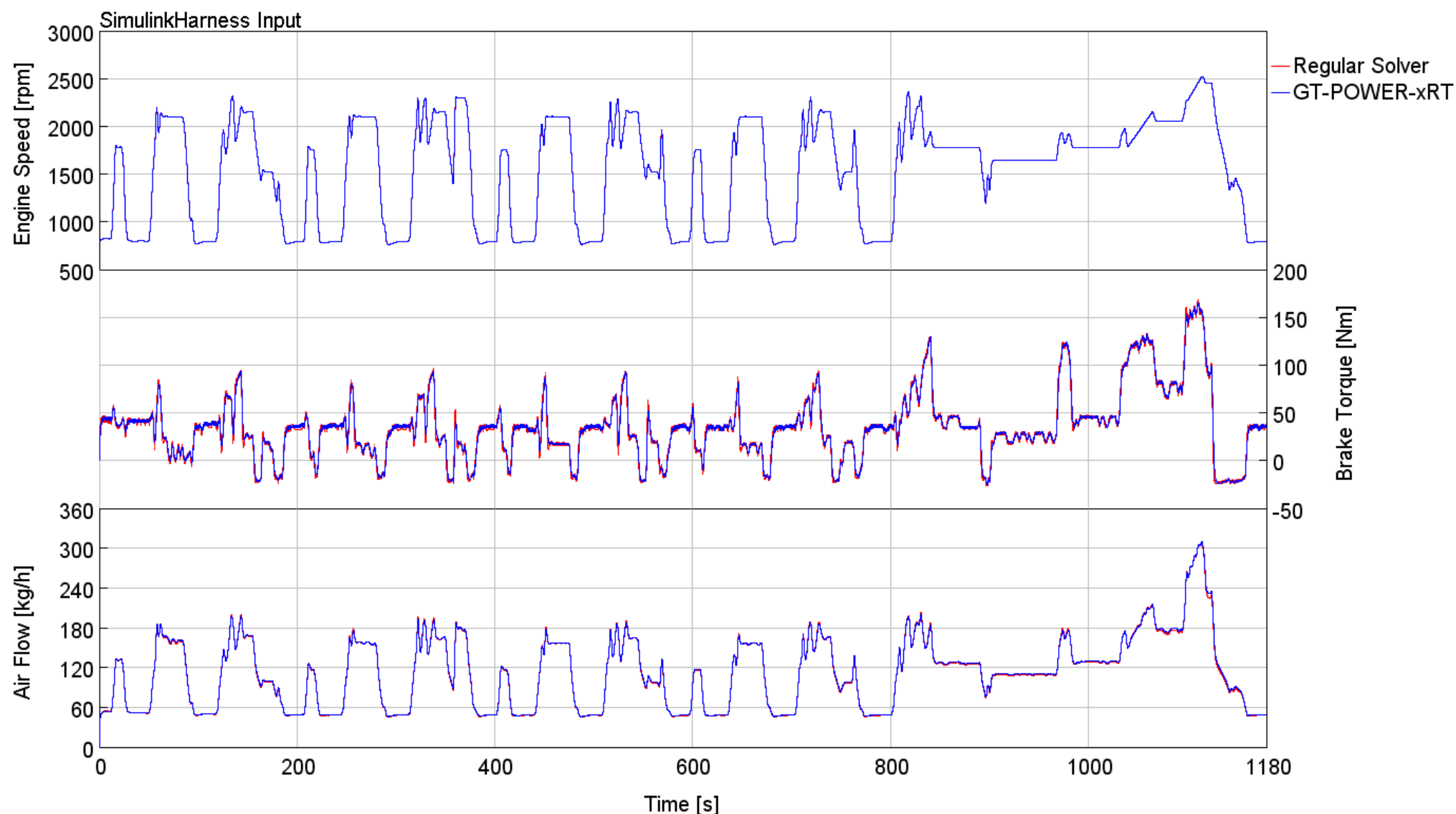


- 运行时对比:
- 常规求解器与GT-POWER-xRT
- NEDC驾驶循环
- 2.0L 4缸柴油机
- 燃烧: 预测性 DIPulsee
- 气缸传热模型: 预测性的 EngCylTWallSoln
- 计算时间的因数对比

Regular Solver : 24.0

GT-POWER-xRT : 2.2!

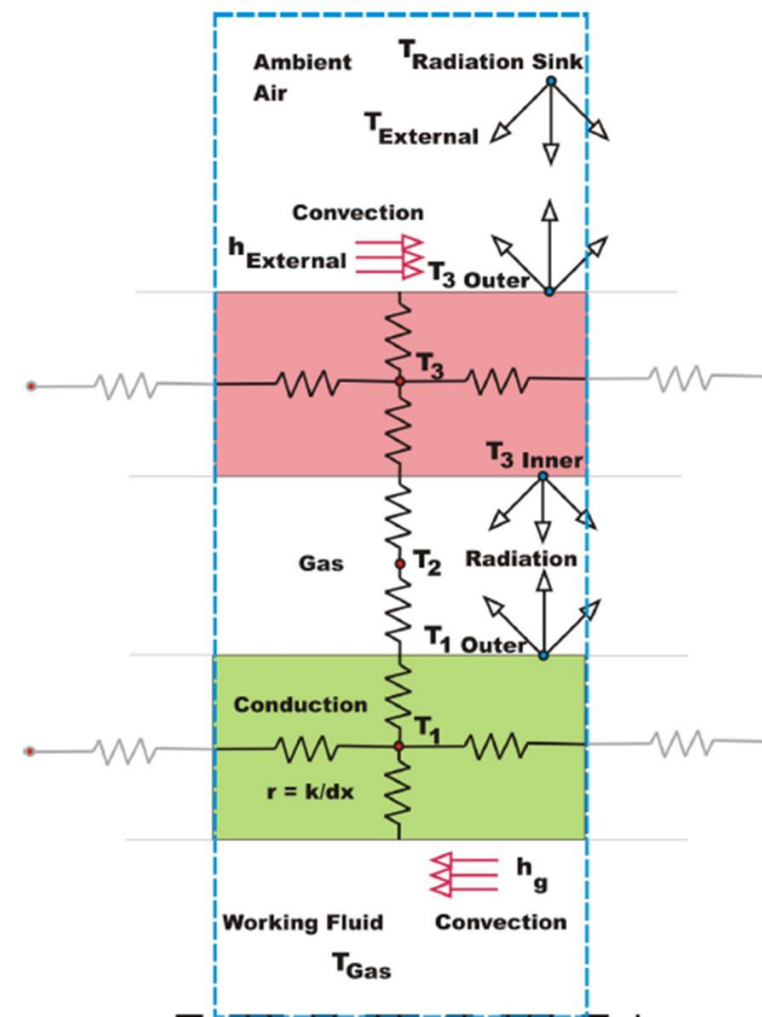
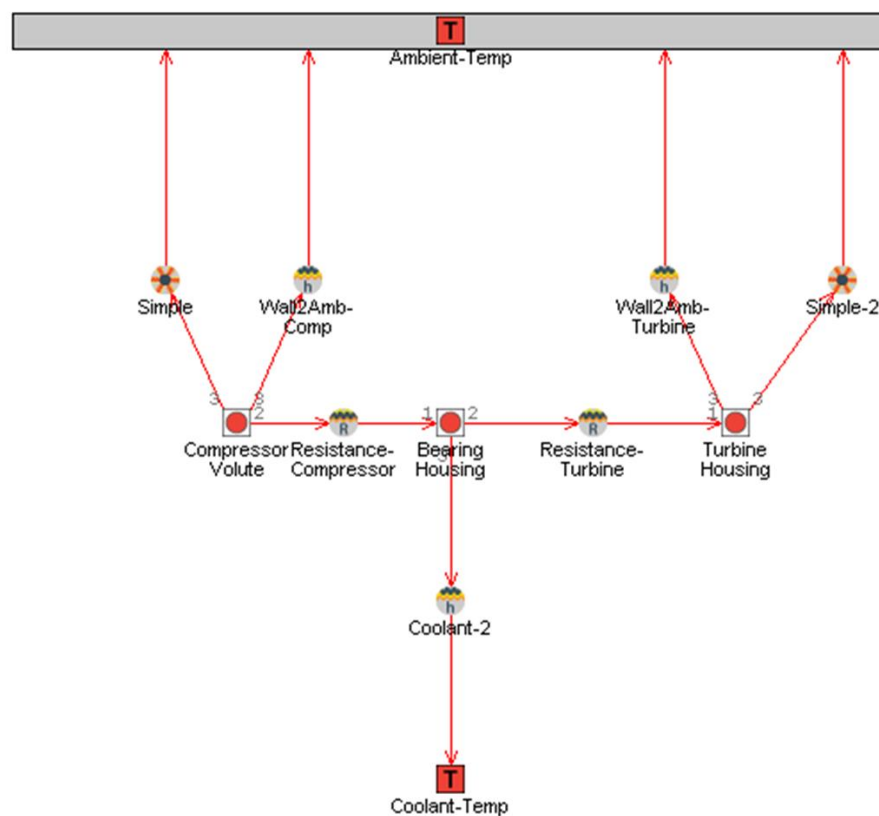




■ Very good correlation between Regular Solver & GT-POWER-xRT

■ 应用:

- 涡轮的热模拟
- 歧管的热模拟



■ 发动机控制应用的爆震预测

● 可用选项:

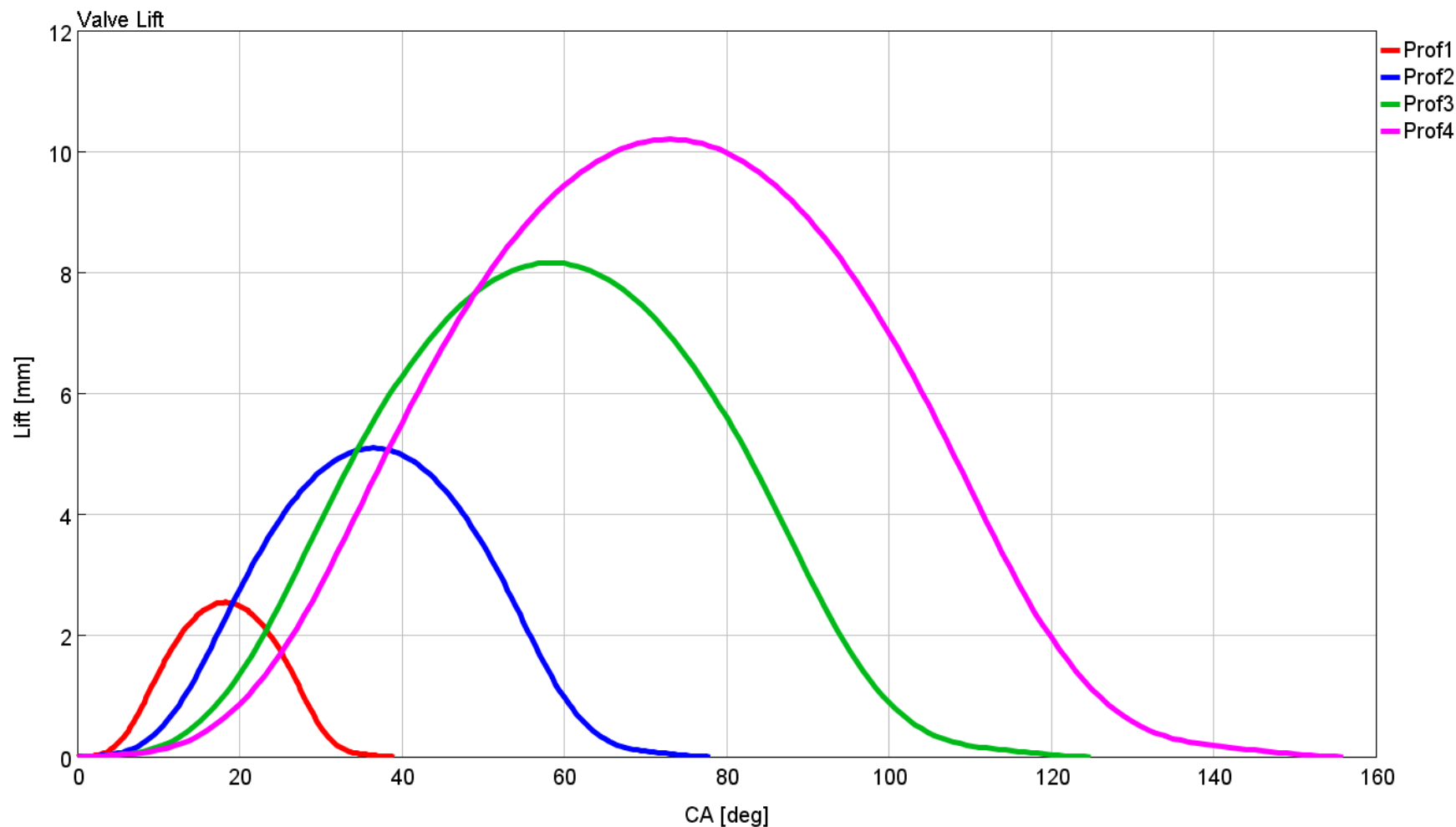
- Kinetics-Fit-Gasoline
- Kinetics-Fit-Gasoline-Ethanol-Blend
- Kinetics-Fit-Natural-Gas
- Douaud&Eyzat

■ 预测性的分层燃烧区 NOX排放模型 (DIPulse v2020 b1)

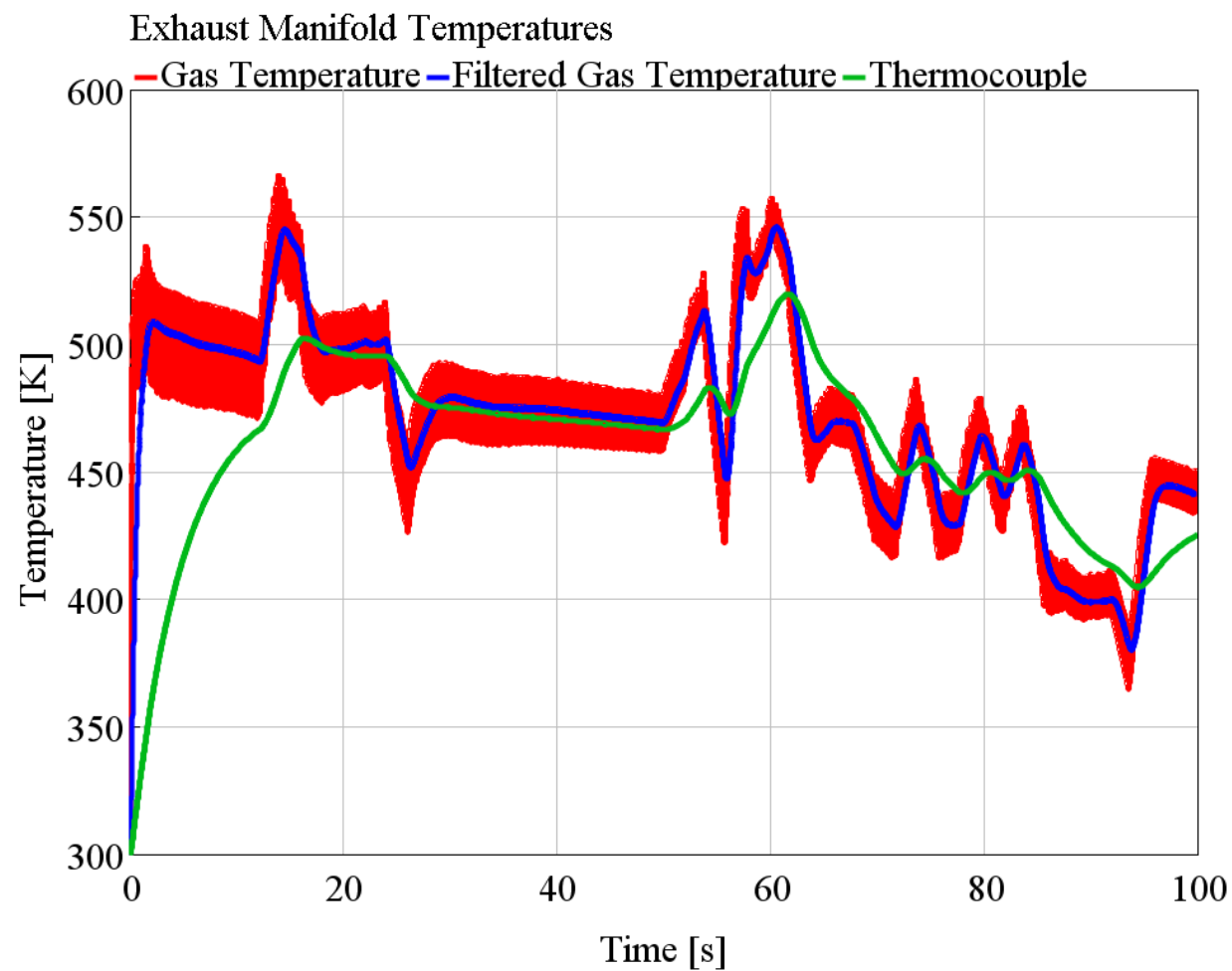
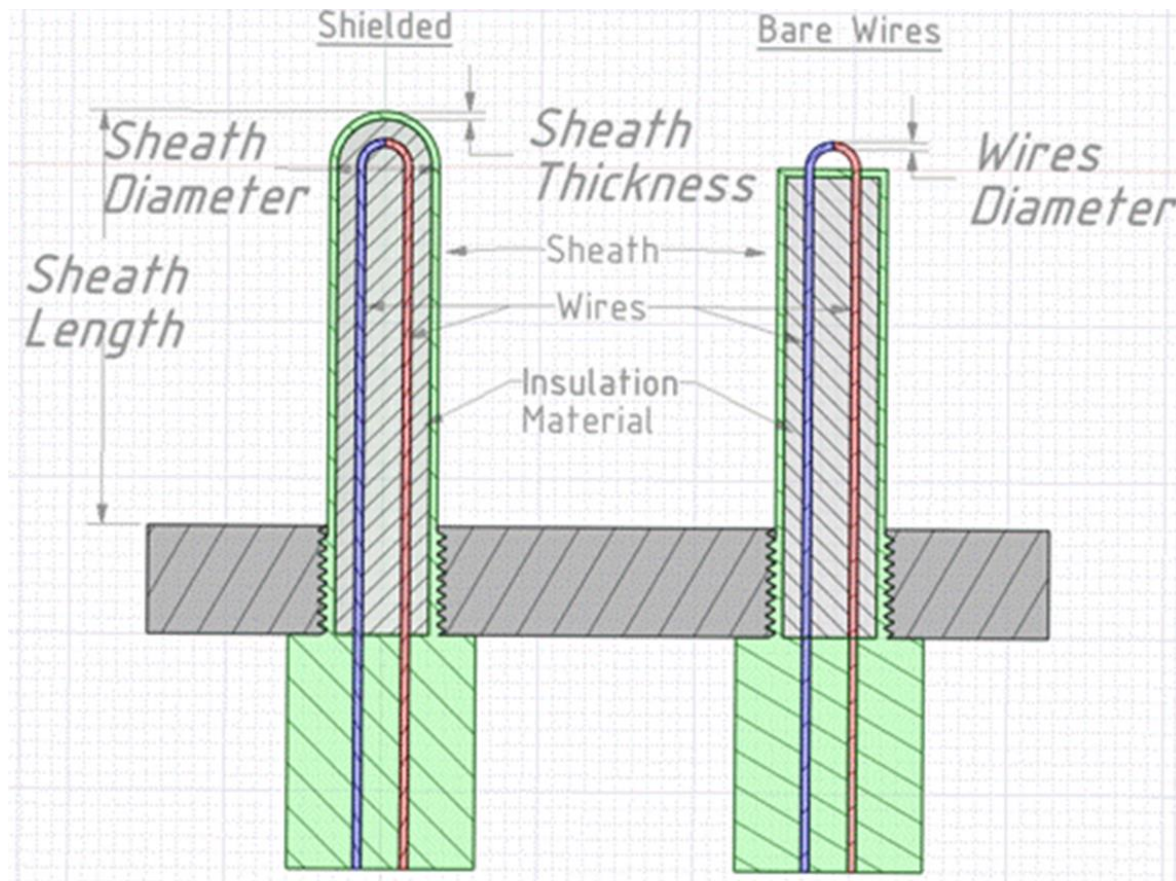
● 内置的 extended Zeldovich mechanism



- XYTableOfMaps for RLTDependence
- 常见的使用：SI发动机的可变升程

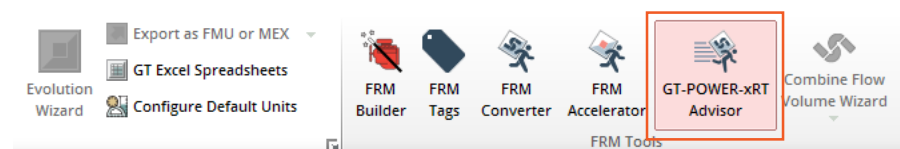


■ 支持热电偶测量比较和控制输入



- 监测任意流体部件的组分浓度 v2020 RC 和 v2019 b3
- 发动机气缸，监测燃烧始点燃烧质量百分数 v2020RC
- 汽缸已燃和未燃烧温度 v2020RC
- RLTDependenceXY 选项输出(Y) =输入(X) v2019 b2
- TurbineMapVGT v2019 b3

- 确保更快的转换过程
- 适用于GT-POWER-xRT设置
- 能够更好地比较结果



GT-POWER-xRT Model Analyzer

Itemized Recommendations

The following attributes are recommended to be set prior to converting this model into a GT-POWER-xRT model. GT-POWER-xRT models have fewer attributes compared to GT-POWER models, and these recommendations will allow you to evaluate the impact of the attributes being removed. This will help assess the results changes expected when switching to a GT-POWER-xRT model.

Attribute Name	Template	Object/Part	Unit	Current Value	Recommended Value	New Value
Air Mass Flow Rate	InjAFSeqConn	SeqInjector	g/s	☐	☒	☒
Initialization State	Run Setup	Initialization		previous_case ▾	user_imposed ▾	user_imposed ▾
Part Attributes	Run Setup	Initialization			on	on
Fixed Time Step Size (Overrides Flow and Mech Step)	Advanced Setup	General	s	ign		Manual change ...

Print List

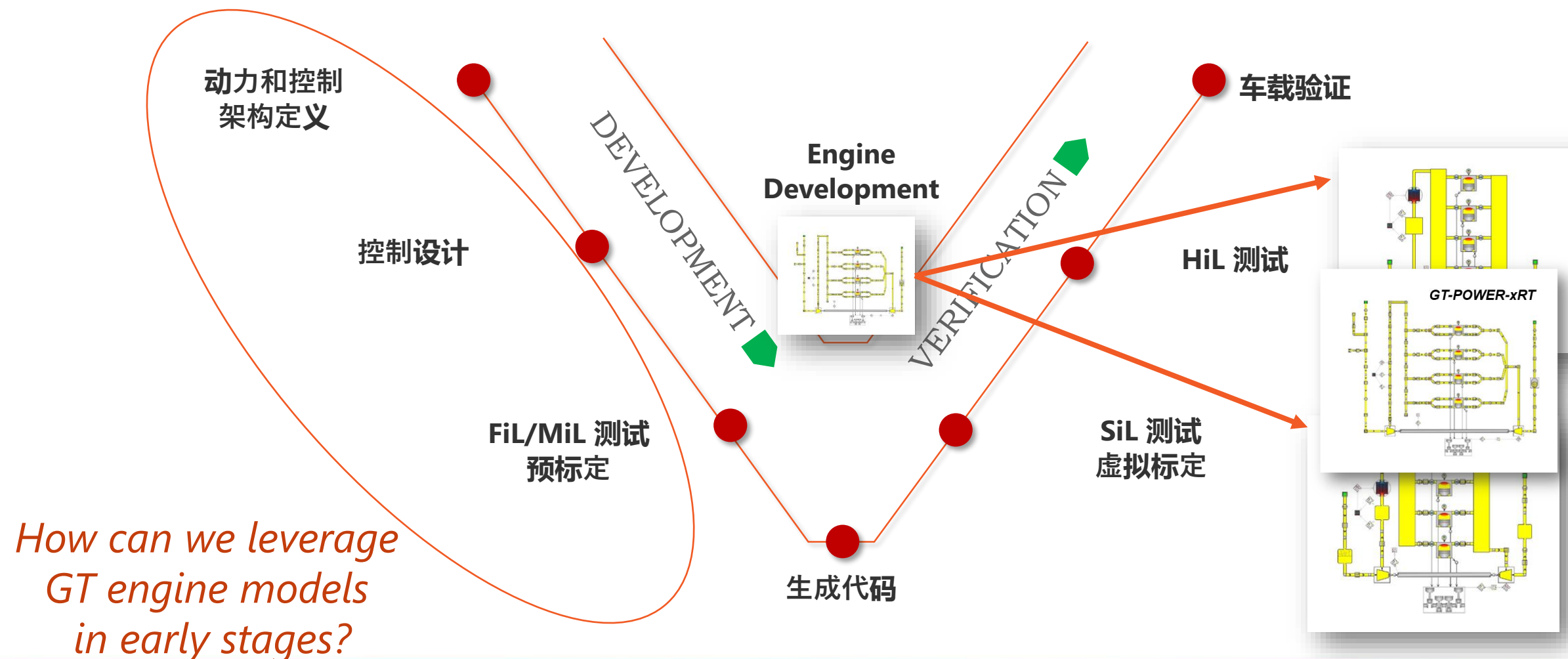
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Finish

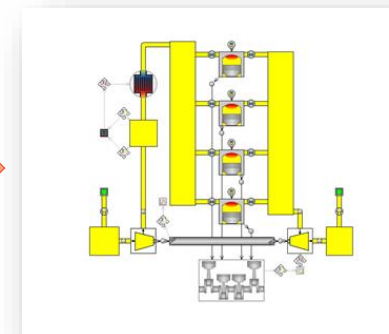
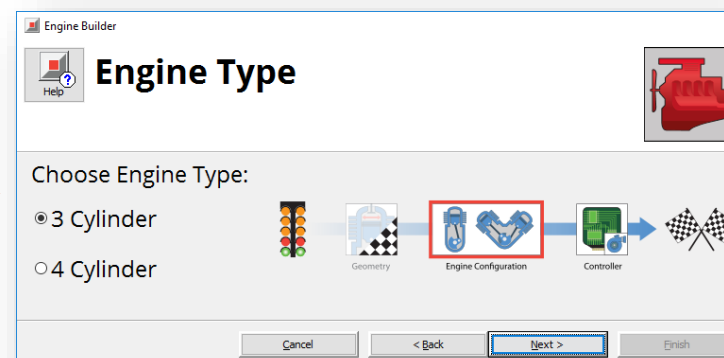
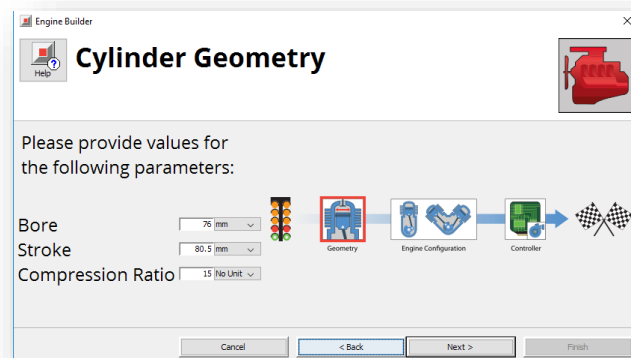
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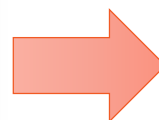
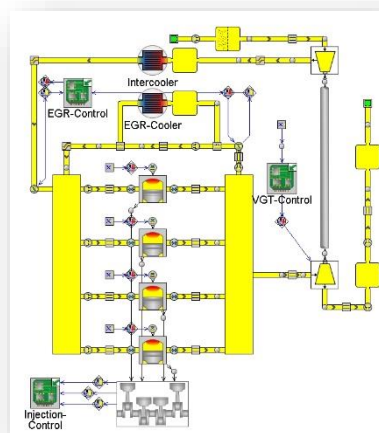
典型的ECU开发周期



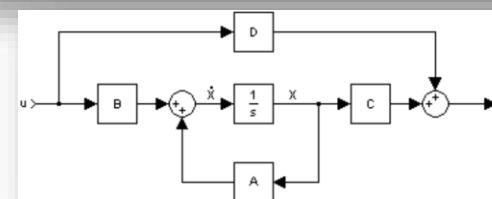
■ FRM-d



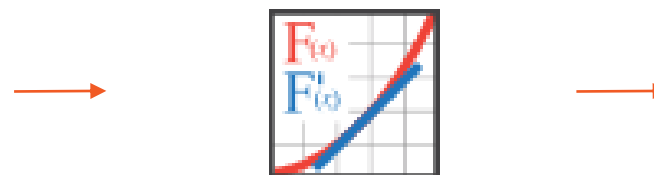
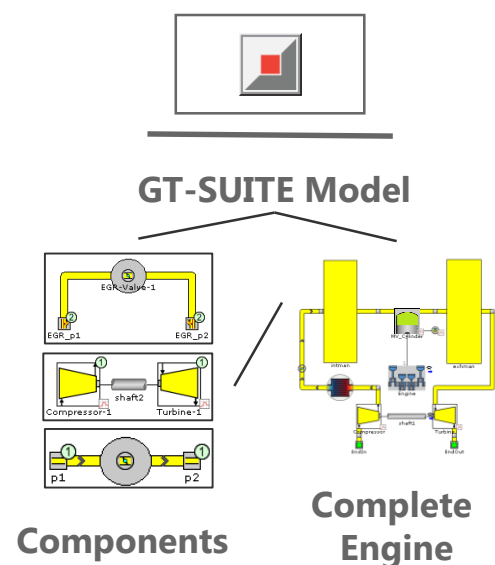
■ 线性化模块



$$\begin{aligned}\dot{\mathbf{x}}(t) &= \mathbf{A}(t)\mathbf{x}(t) + \mathbf{B}(t)\mathbf{u}(t) \\ \mathbf{y}(t) &= \mathbf{C}(t)\mathbf{x}(t) + \mathbf{D}(t)\mathbf{u}(t)\end{aligned}$$



Linearization with GT

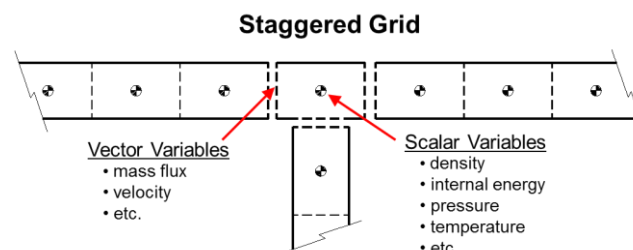


Direct Linearization of Navier Stokes 1D equations in GT around an operating point

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_j} [\rho u_j] = 0$$

$$\frac{\partial}{\partial t} (\rho u_i) + \frac{\partial}{\partial x_j} [\rho u_i u_j + p \delta_{ij} - \tau_{ji}] = 0$$

$$\frac{\partial}{\partial t} (\rho e_0) + \frac{\partial}{\partial x_j} [\rho u_j e_0 + u_j p + q_j - u_i \tau_{ij}] = 0$$



$$\delta \dot{x} = \mathbf{A} \cdot \delta x + \mathbf{B} \cdot \delta u$$

$$\delta y = \mathbf{C} \cdot \delta x + \mathbf{D} \cdot \delta u$$

MeanV-final-V2020_C008_L01_matrixA.csv

MeanV-final-V2020_C008_L01_matrixB.csv

MeanV-final-V2020_C008_L01_matrixC.csv

MeanV-final-V2020_C008_L01_matrixD.csv

MeanV-final-V2020_C008_L01_namesInputs.csv

MeanV-final-V2020_C008_L01_namesOutputs.csv

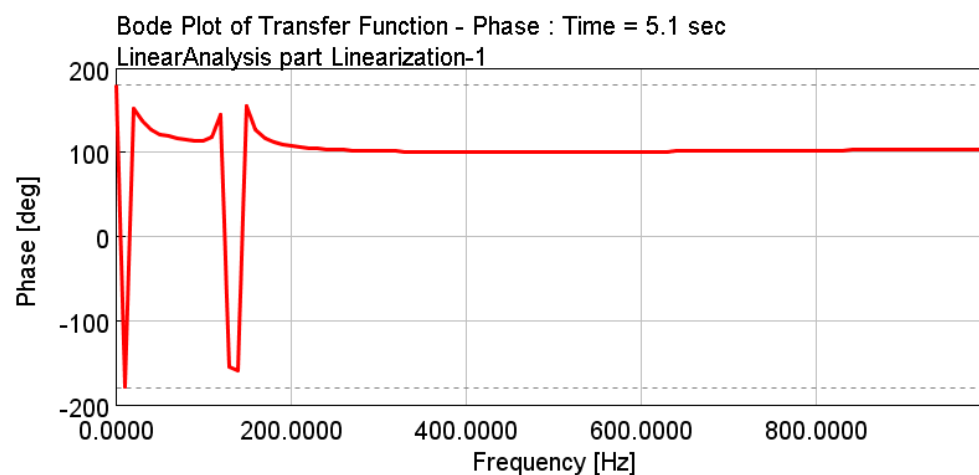
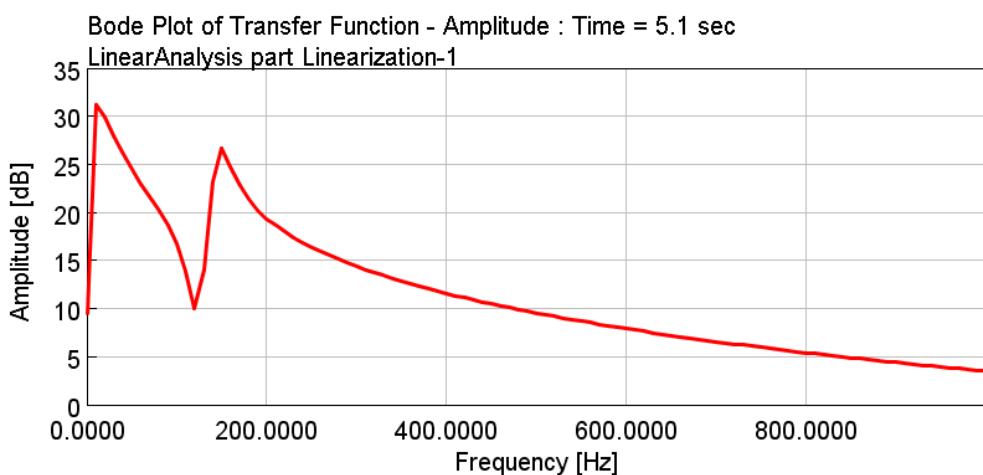
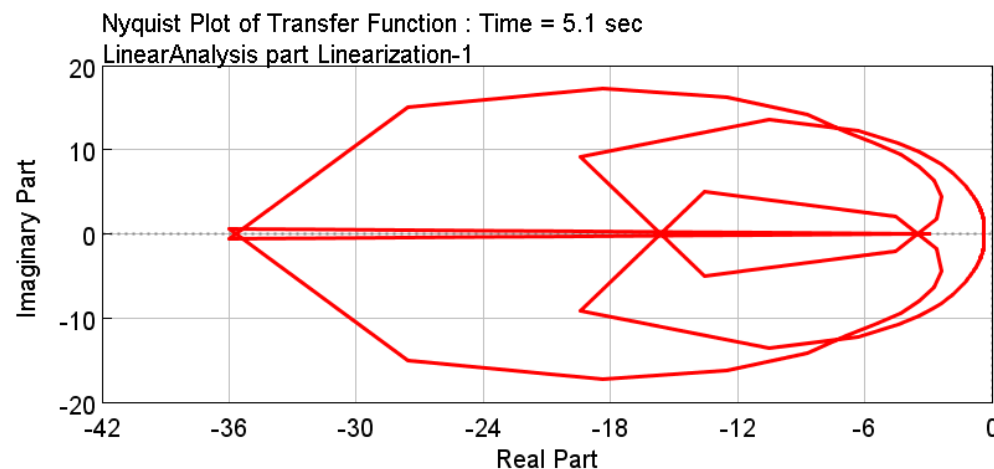
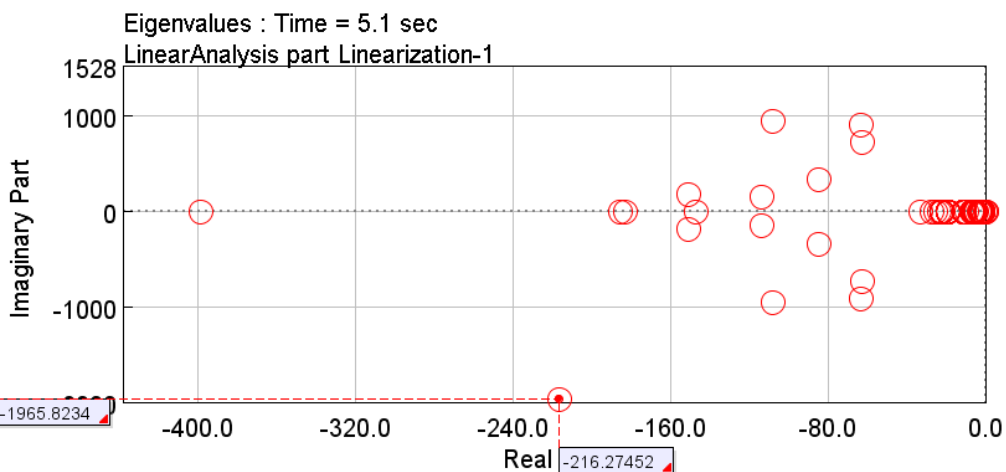
MeanV-final-V2020_C008_L01_namesStates.csv

- 直接基于物理的线性模型
- 不需要一步一步的识别线性系统
- 访问所有向量和标量变量
- 考虑系统和相关控制器之间的交互和相互依赖关系的可能性

⇒ **Multi-variables Control Design**

■ 输出 Eigenvalues, Bode Plots, Nyquist

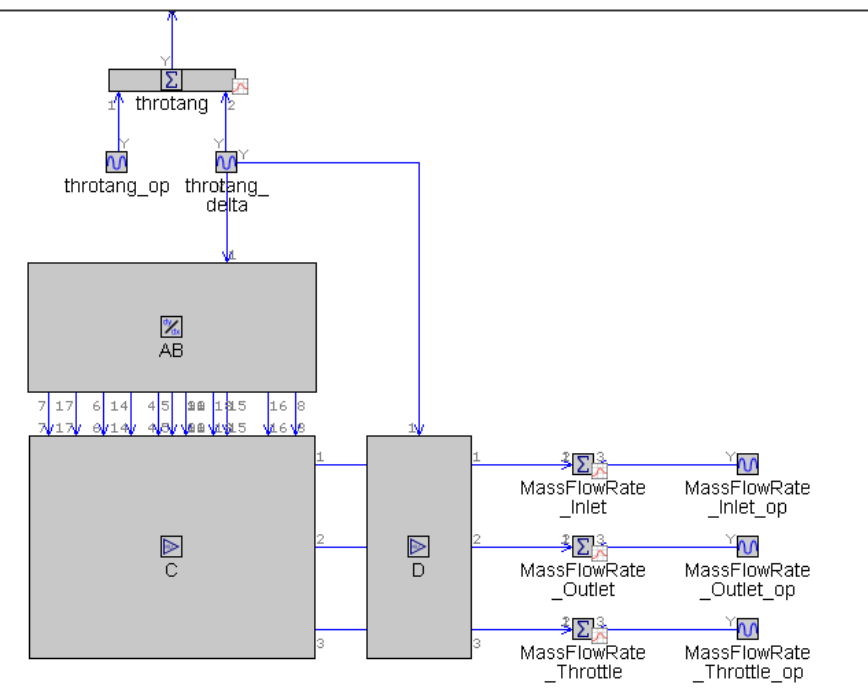
- 有助于理解系统的动态行为(甚至不运行模型)



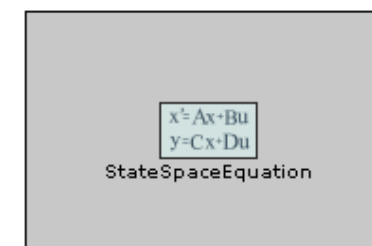
■ 新模型 StateSpaceEquation

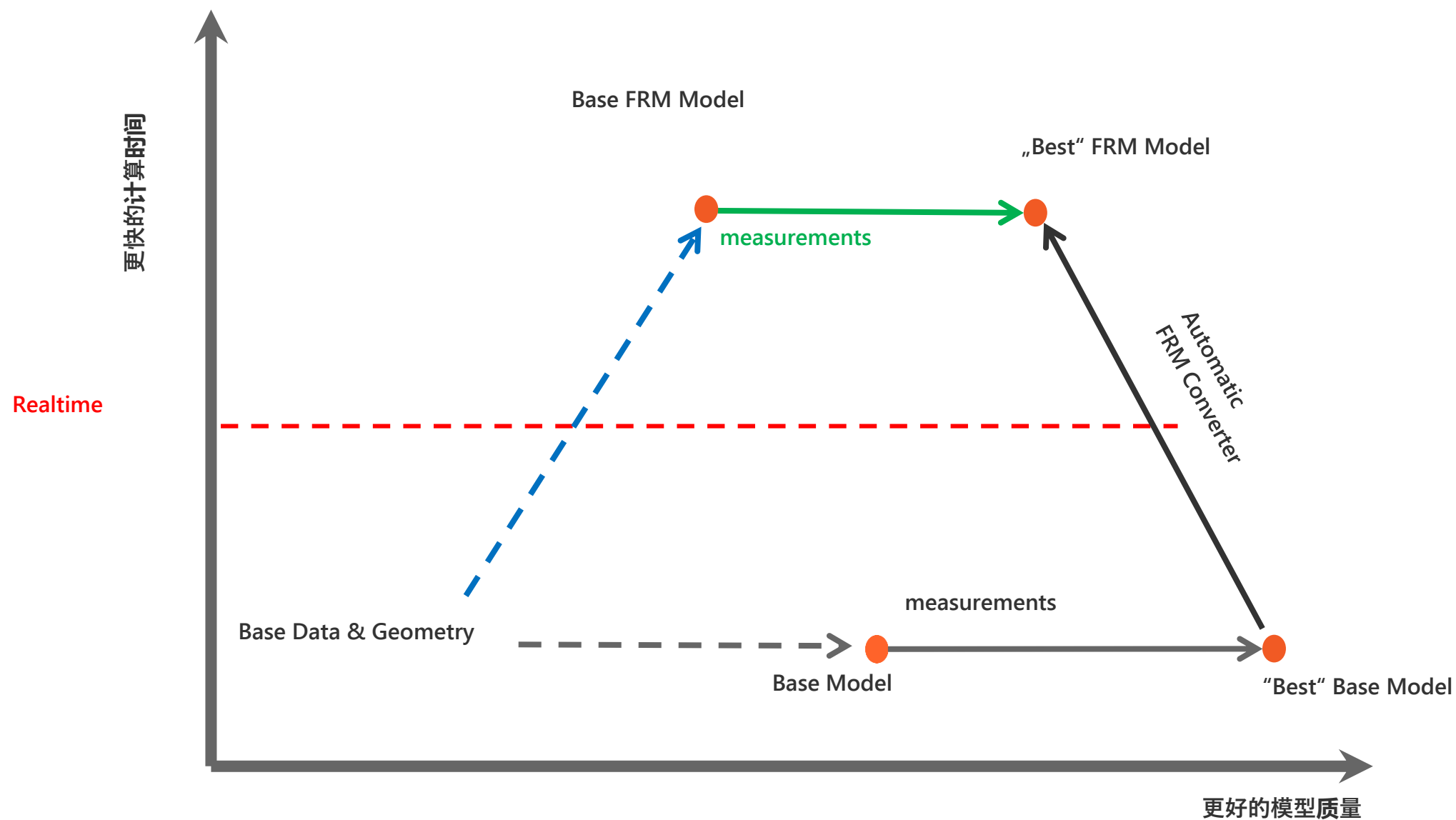
- 直接使用“线性分析”生成的状态空间矩阵
- 更快(从1小时到1分钟)，验证模型的设置更少出错

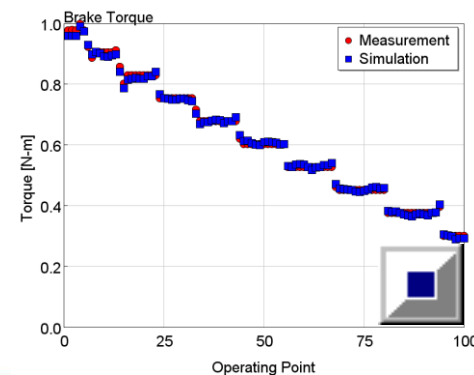
v2019



v2020

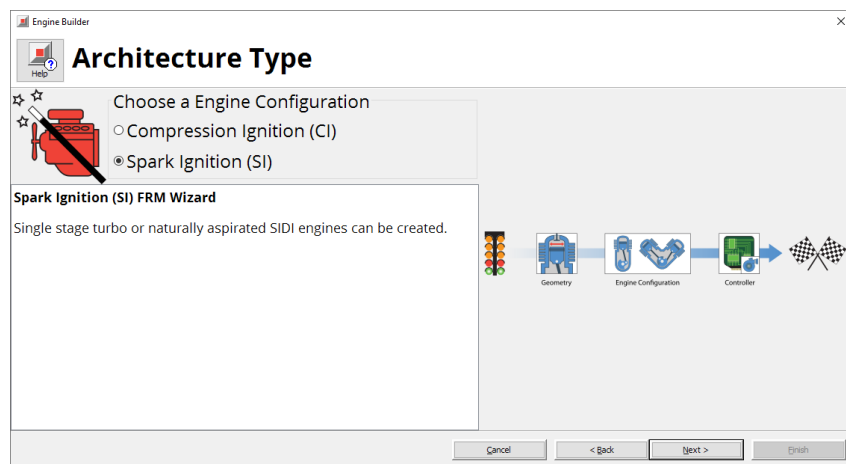






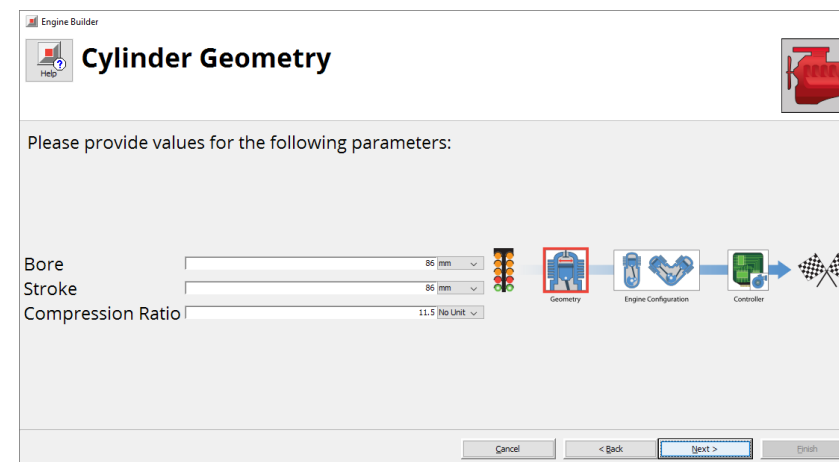
Step 1

创建
FRM

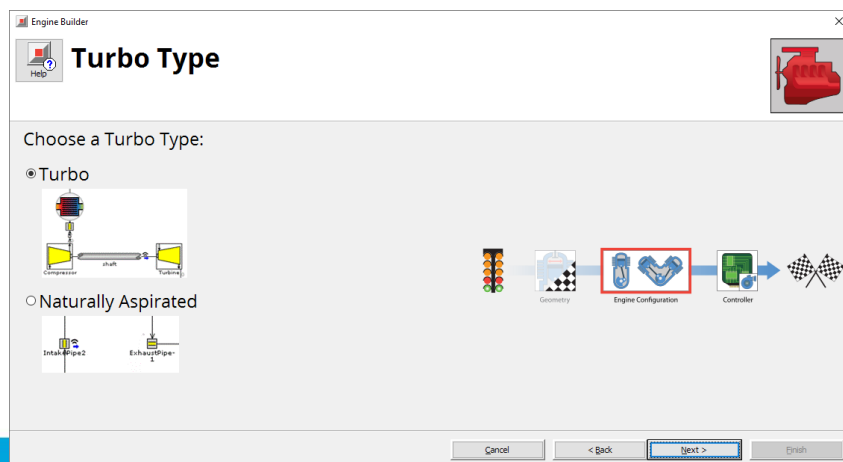


Step 2

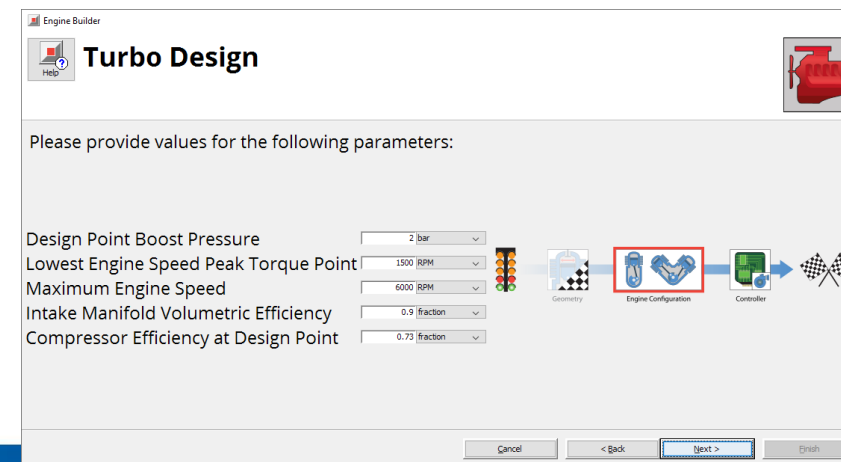
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Step 3

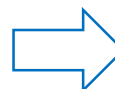


Step 4
增压器输入

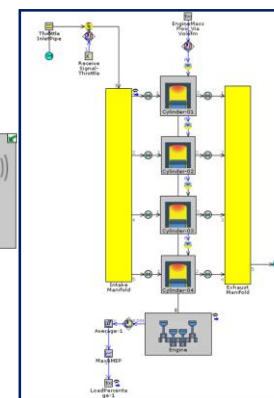


Step 6

Finish



The screenshot displays the GT-IDE v2019 - GT-POWER v2019 software interface. The top menu bar includes File, Home, View, Data, Tools, HMC, and INHOUSE. Below the menu is a toolbar with icons for Open, Save, Compare Files, Recommended Changes, Delete Unused Objects, FRM Builder, FRM Tags, FRM Converter, FRM Accelerator, Combine Flow, Volume Wizard, Case Setup, Plot Setup, Output Setup, Advanced Setup, Design Optimizer, Run, View Results, and Stop. The main workspace is divided into several panes. On the left is the 'Mini Map' showing the 'GT-POWER Application' tree with folders for Flow, Components, Connections, and References. The central area shows a 3D model of an engine (FRM_Engine) connected to a 2D schematic of the FRM_Subassembly. A large blue arrow points from the 3D model to the 2D schematic. Below the 2D schematic is a text box stating: 'If coupled to Simulink via selected in the FRM Builder 1 additional Link between Controller and SendSignal parts is needed. Connect the Simulinkmass to the Throttle Angle input of SendSignal.' The right side of the interface shows a 'Preprocessor' pane with a 'Run' button and a 'View Results' button. The bottom right corner shows a 'SendSignal' block connected to a 'Controller' block, which is connected to a 'ReceivingController' block. The 'SendSignal' block has an input for 'Angle' and an output for 'Throttle'.



FileHomeInsertPage LayoutFormulasDataReviewViewHelpTell me what you want to do

CutCopyFormat Painter

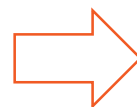
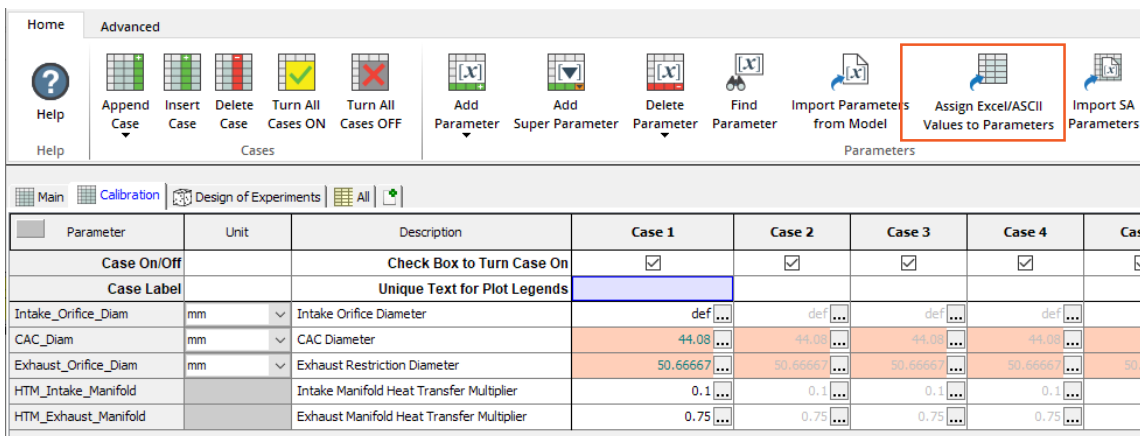
Paste

Clipboard

Calibri11

</

■ 引导选项指向Excel数据



Global Excel/Ascii Data Import Wizard

Help

Define Options

Importing data from: D:\temp\FRMBuilderData.xlsx, FRMBuilderData
 New parameters that do not currently exist in Case Setup are shown in blue text. They will be added to Case Setup after clicking Finish.

Populate All Empty Parameter Fields

	A	B	C	D	E	F	
☒ ImportData?	☒	☒	☒	☒	☒	☒	
Parameter	OperatingPoint ...	Engine_Speed ...	Brake_Torque ...	Brake_Power ...	BSFC ...	BMEP ...	Volum
Label	OperatingPoint	Engine Speed	Brake Torque	Brake Power	BSFC	BMEP	Volum
Unit	No Unit (empty) ...	RPM	N-m	kW	g/kW-h	bar	fractic
1	1	1000	165	18	246	10.9	0.93
2	2	1500	260	41	256	17.2	1.52
3	3	2000	289	61	294	19.1	1.70
4	4	2500	290	76	293	19.2	1.65
5	5	3000	298	94	287	19.7	1.66
6	6	3500	295	108	281	19.5	1.58
7	7	4000	294	123	269	19.4	1.55
8	8	4500	291	137	282	19.3	1.56
9	9	5000	282	148	294	18.7	1.53
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FRMBuilderData
Sheet1

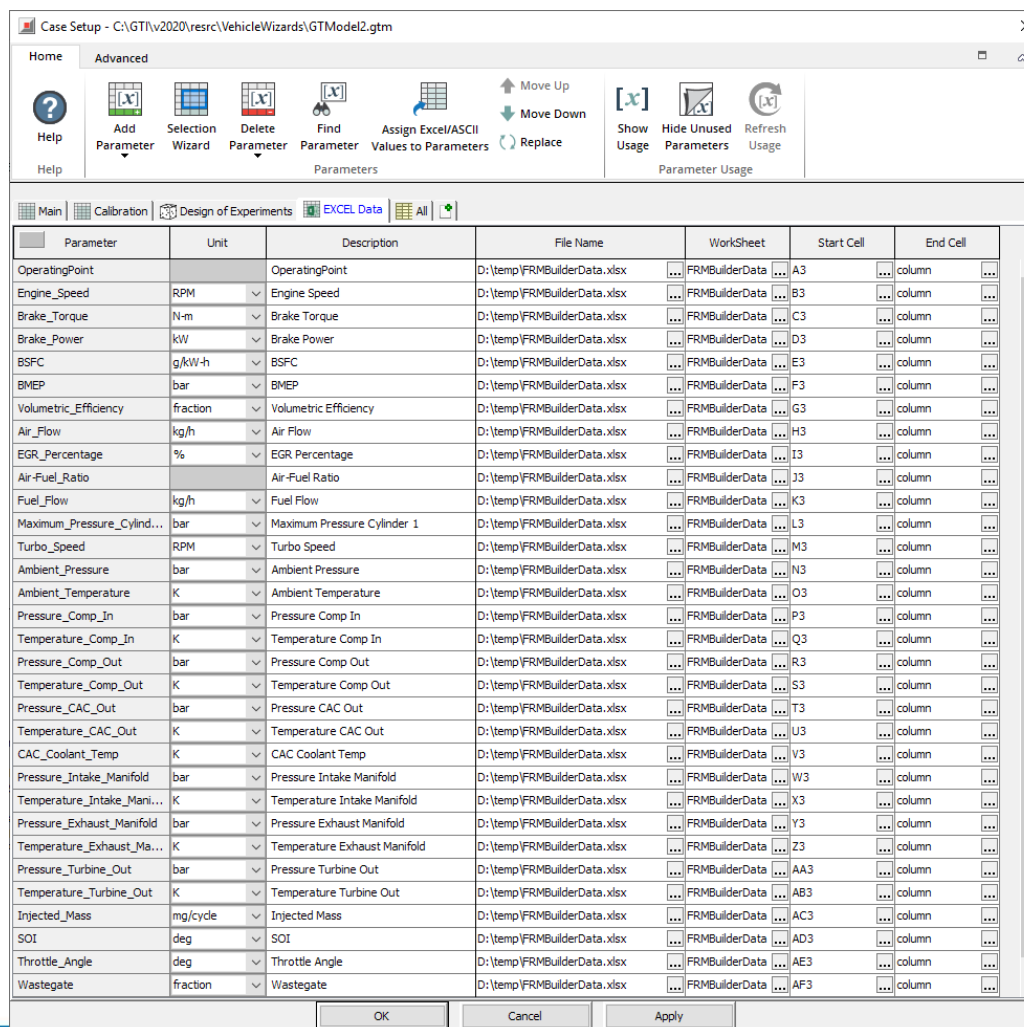
Cancel

< Back

Next >

Finish

■ 在 Case Setup 中快速设置参数



■ 使用 Design Optimizer 标定

Design Optimizer

Home Data

Template Documentation Attribute Abilities

License Type: GT-POWER

Model Name: D:\training\2019_EU_Conference\Seminar\FRM-d\GTModel2.gtm

Model Information

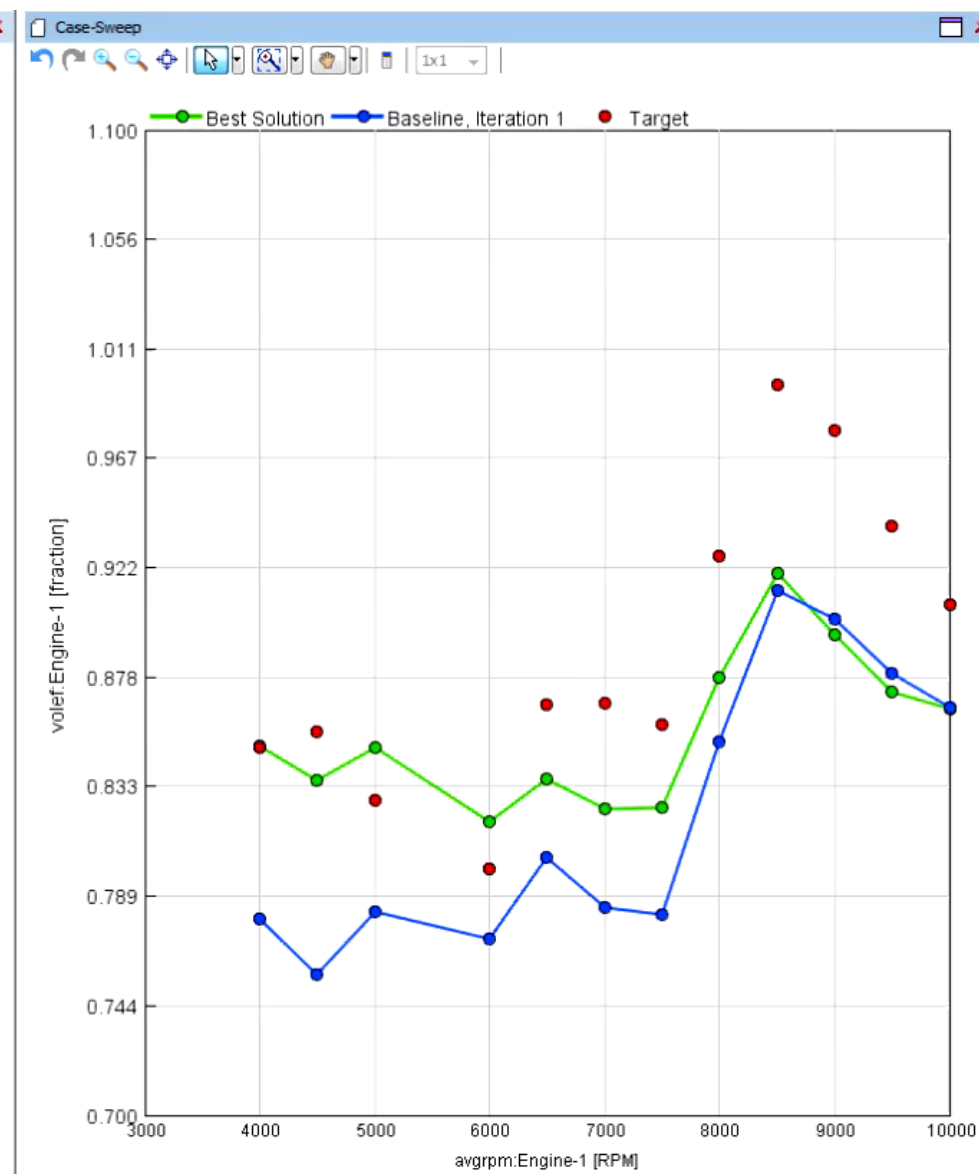
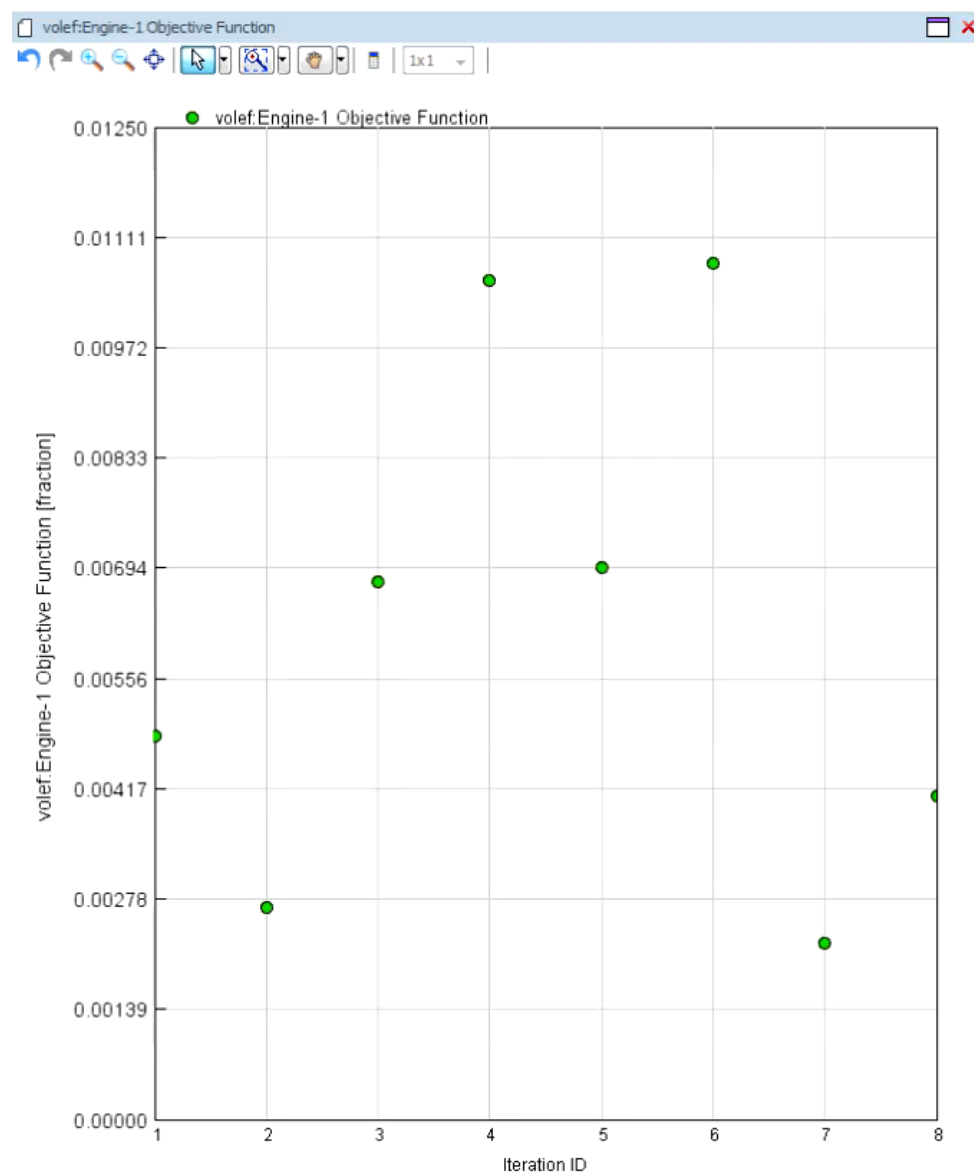
✓ Main ✓ Constraints

Attribute	Object Value
☐ OFF	
☒ Integrated Design Optimizer	
☐ Simple Optimizer	
Optimization Type	
☒ Single Objective	
☐ Multi-Objective, Pareto	
☐ Multi-Objective, Weighted-Sum	
☐ Transient Targeting	
Case Handling	
☒ Optimize Each Case Independently	
☐ Case Sweep and Cross-Case Studies	
Search Algorithm	
Maximum Number of Designs	def...
Search Algorithm	Simplex
Integrated Design Optimizer Options	
Optimization Restart File	ign...
Faster Runtime (Local Runs Only)	☒
Maximum Number of Parallel Designs	1
Timeout Duration (minutes)	60
Save Design Files?	☐
Automatic Data Suppression (Recommended)	☒

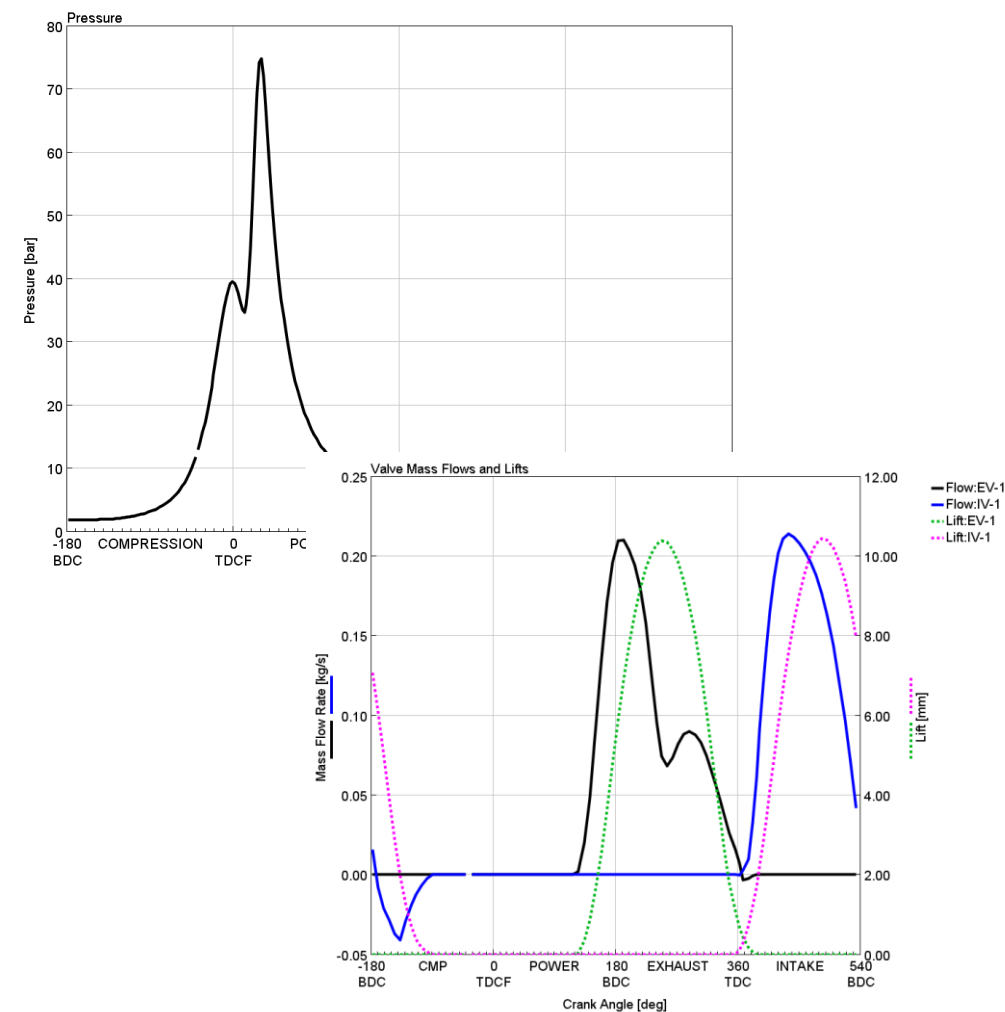
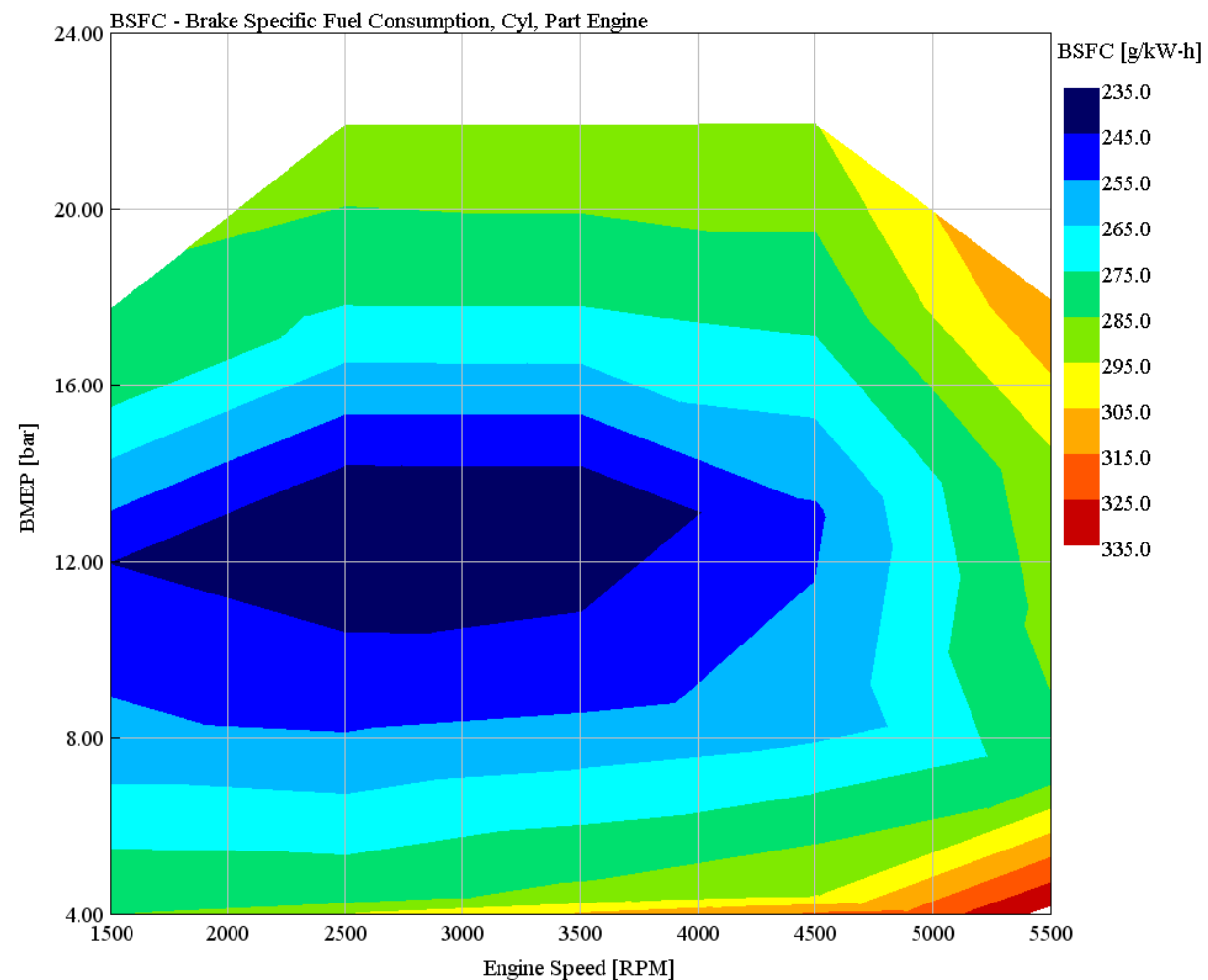
Attribute	1	2	3
Factors - Choose from among parameters that already exist in Case Set			
Factor	HTM_Exhaust...		
☐ Range			
☒ Lower Limit	0.1		
Upper Limit	4		
Resolution (% of Range)	1		
Integers Only	☐	☐	☐

Attribute	1	2
Response RLTs and Objectives		
Response RLT	volef:Engine	
Objective	Target	
Target Value	[volef_target]	

OK Cancel Apply



■ Results:



- 在优化器中设置
- 最小化均方差的自动化

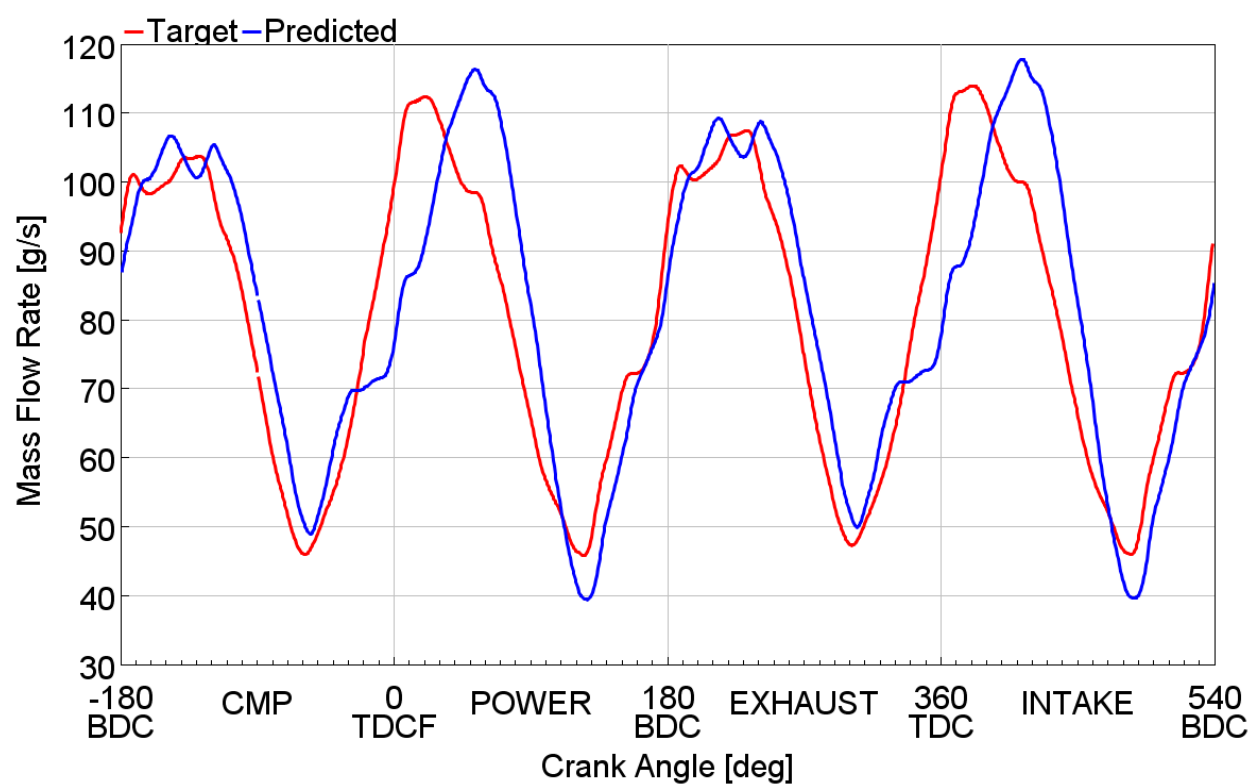
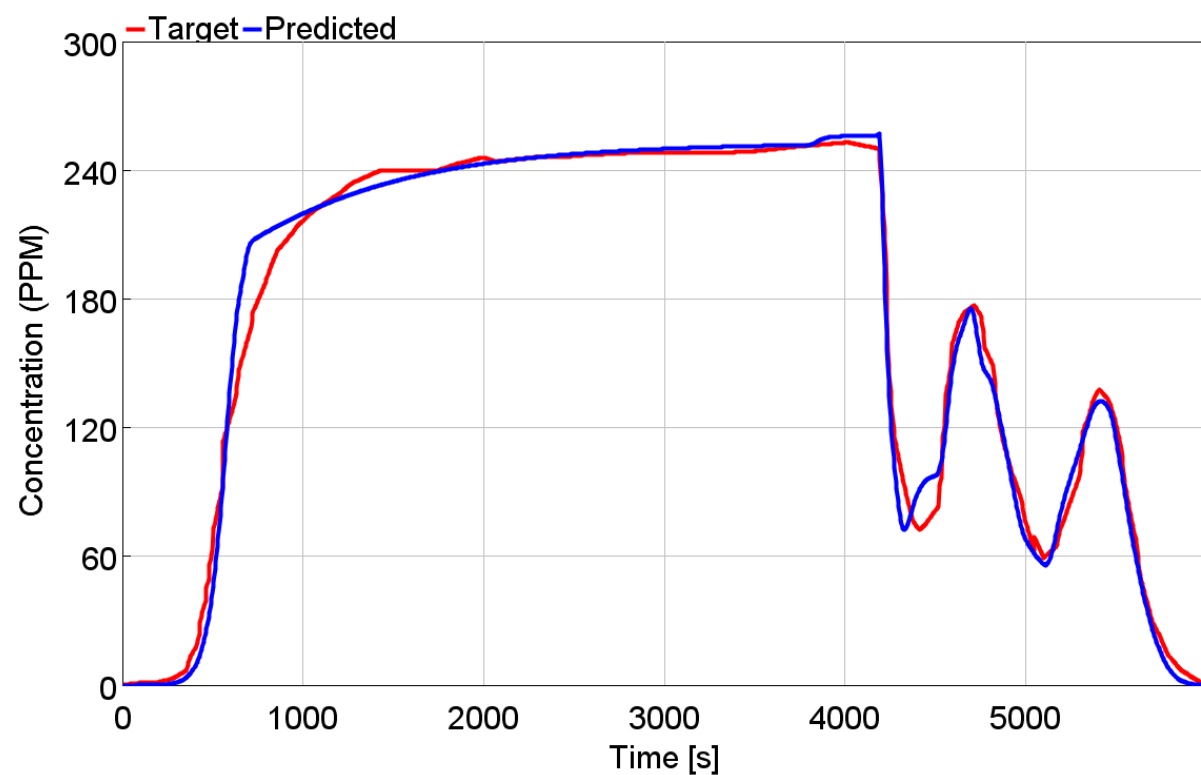
✓ Main

✓ Constraints

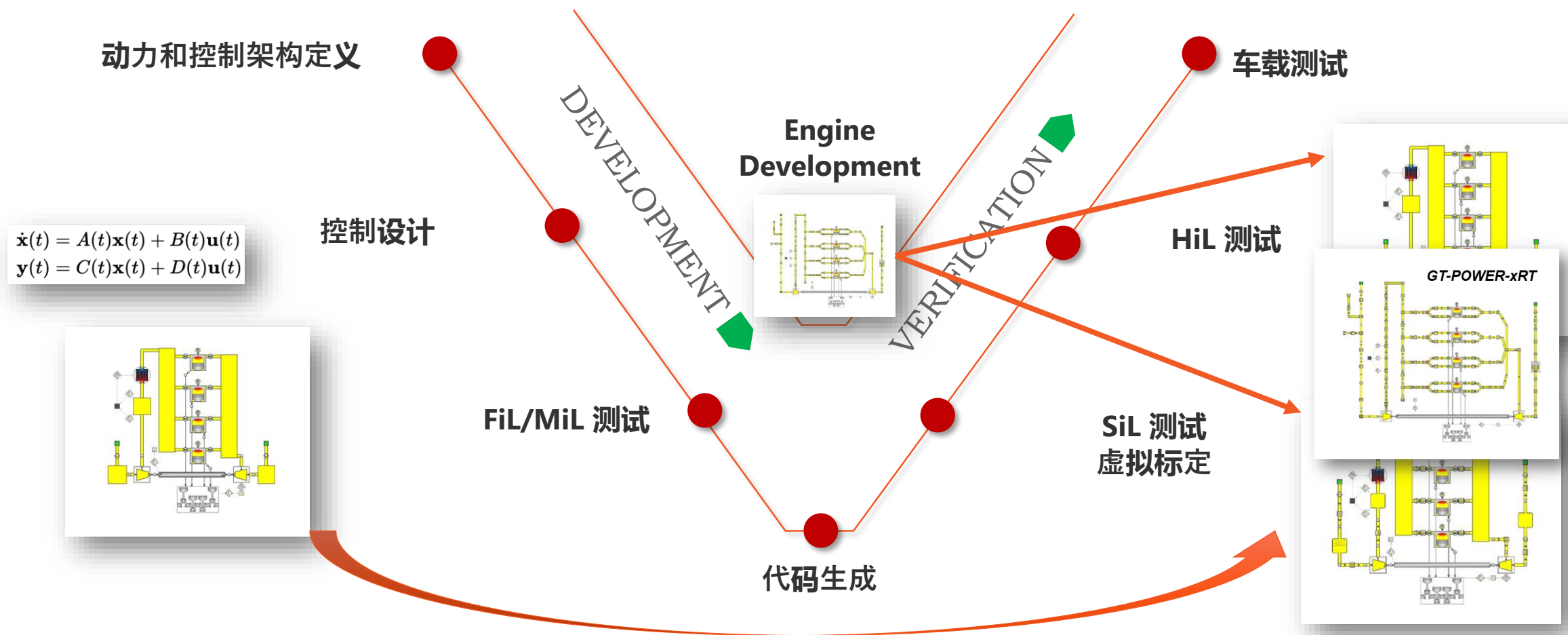
	Attribute	Object Value
☐	OFF	
☒	Integrated Design Optimizer	
☐	Simple Optimizer	
Optimization Type		
☐	Single Objective	
☐	Multi-Objective, Pareto	
☐	Multi-Objective, Weighted-Sum	
☒	Transient Targeting	
	Integration Basis	LastCycle
Case Handling		EntireRun
☒	Optimize Each Case Independently	LastCycle
☐	Case Swap and Case Case Studies	

Attribute	Unit	1	2	3
Transient Targeting				
Signal or Time RLT		btq:Engine ...	1:Collector 1:25:25 ...	2:ExPipe:32:32 ...
Target Profile		Torque_Profile ...	Meas_Exh_Pressure ...	Meas_Exh_Temperature ...
Term Weight		def (=1) ...	def (=1) ...	def (=1) ...
Start Time	s	def (=0) ...	def (=0) ...	def (=0) ...
End Time	s	def (=case end) ...	def (=case end) ...	def (=case end) ...

■ 标定瞬态信号和TimeRLTs与试验结果



GT-SUITE 可以在整个开发周期中使用

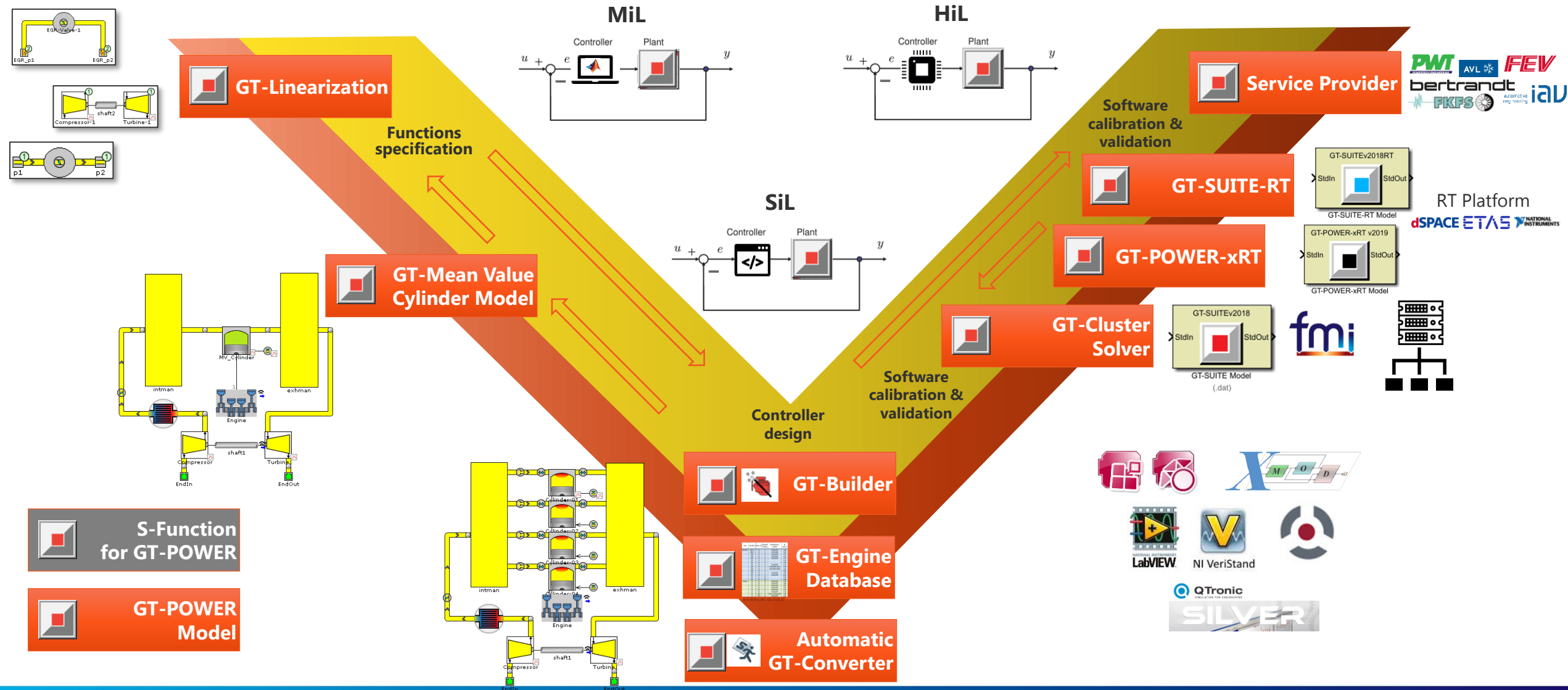


■ 模拟

- 确保可预测性并最大化测量数据的效果
- 保持模型拓扑和建模元素
- 能够满足对模型复杂性/速度的广泛需求

■ 工作流程

- 利用现有的GT模型或支持从空白页创建
- 单一工具贯穿整个开发周期、组间的公共语言、共享的子系统模型
- 更好的可跟踪性和模型管理
- 快速的计算时间，便于通过试验数据增强模型实用性
- 与MATLAB/Simulink和标定/验证平台无缝连接



感谢倾听
期待与您合作 😊



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